A Comparative Study On Initial Value Problems (IVP) for

Ordinary Differential Equations (ODE) with Euler's,

Euler's Modified, Picard's and Runge Kutta Methods

Surender Kumar Srivastav¹, Salma Khan², Waikhom Rojen Singh³

¹Assistant Professor, Department of Science, Jayoti Vidyapeeth Women's University, Jaipur

(Rajasthan)

²Research Scholar, Jayoti Vidyapeeth Women's University, Jaipur (Rajasthan)

³Assistant Professor, Department of Science, Jayoti Vidyapeeth Women's University, Jaipur

(Rajasthan)

Email Id: salma1306khan@gmail.com

ABSTRACT:

This paper presents different numerical method for the solution of ordinary differential equations.

We consider the first order differential equation dy/dx = f(x, y) with the initial condition $y(x_0) =$

y₀. We can solve the ordinary differential equations by using the following methods Euler's

Method, Euler's Modified Method, Picard's Method and Runge-Kutta Method. In order to verify

the accuracy, we compare numerical solutions with exact solutions. The numerical solutions are

in good agreement with the exact solutions. Numerical comparisons between these methods have

been presented. Also we compare the performance and the computational effort of such methods.

KEYWORDS: Initial Value Problem (IVP), Ordinary Differential Equation (ODE), Euler's

Method, Euler's Modified Method, Picard's Method, Runge-Kutta Method.

INTRODUCTION:

Differential equations are commonly used for mathematical modeling in science and engineering.

Many problems of mathematical physics can be started in the form of differential equations.

These equations also occur as reformulations of other mathematical problems such as ordinary

differential equations and partial differential equations. In most real life situations, the

differential equation models the problem that are too complicated to solve exactly, and one of

two approaches is taken to approximate the solution. The first approach is to simplify the

1

differential equation to one that can be solved exactly and use the solution of the simplified equation to approximate the solution to the original equation. The other approach uses methods for approximating the solution of original problem. This is the approach that is most commonly taken as the approximation methods give more accurate results and realistic error information. Numerical methods are generally used for solving mathematical problems that are formulated in science and engineering where it is difficult and sometime impossible for calculated exact solutions. There are a few differential equations that can be solved analytically. There are many analytical methods for finding the solution of ordinary differential equations. But there are large number of ordinary differential equations whose solutions cannot be obtained by using well-known analytical methods, in such cases we use the numerical methods for finding the approximate solution of a differential equation under the given initial conditions. There are many types of practical numerical methods for solving initial value problems for ordinary differential equations.

FORMATION OF PROBLEM:

In this section we consider numerical methods for finding the approximate solutions of the initial value problem (IVP) of the first-order ordinary differential equation has the form

$$y' = f(x, y(x)), x \in (x_0, x_n)$$
 with initial condition $y(x_0) = y_0 \dots (i)$

Where y' = dy/dx and f(x, y(x)) is a given function and y(x) is the solution of the equation (i). In this section paper we determine the solution of this equation in a interval (x_0, x_n) , starting with the initial point x_0 . A continuous approximation to the solution y(x) will not be obtained in the interval (x_0, x_n) . Numerical methods apply the equation (i) to obtain approximations to the values of the solution corresponding to various selected values of $x = x_n = x_0 + nh$, n = 1, 2, 3, ... The constant h is called the steps size. The numerical solutions of equation (i) is given by a set of points $\{(x_n, y_n) : n = 0, 1, 2, ..., n\}$ and each point (x_n, y_n) is an approximation to the corresponding point $(x_n, y(x_n))$ on the solution curve.

Euler's Method -

The general formula for Euler's approximation is

$$y_{n+1} = y_n + h f(x_n + y_n), n = 0, 1, 2, 3,$$

Modified Euler's Method -

The general formula for Modified Euler's approximation is

$$y_{n+1} = y_0 + \frac{h}{2} [f(x_0, y_0) + f(x_{n+1}, y_{n+1}^{(1)})]$$

Where
$$y_{n+1}^{(1)} = y_n + h f(x_n, y_n)$$

Picard's method -

The general formula for Picard's approximation is

$$y_n = y_0 + \int_{x_0}^{x} f(x, y_{n-1}) dx$$

Runge-Kutta Method -

Four types of Runge-Kutta method.

(i) Runge-Kutta Method of First Order -

$$y_{n+1} = y_n + h f(x_n, y_n)$$

(ii) Runge-Kutta Method of Second Order -

$$y_{n+1} = y_n + \frac{1}{2} \left(k_1 + k_2 \right)$$

where
$$k_1 = h$$
 f x_n , y_n) and $k_2 = h$ f($x_n + h$, $y_n + k_1$)

(iii) Runge-Kutta Method of third Order -

$$y_{n+1} = y_n + \frac{1}{6}(k_1 + 4 k_2 + k_3)$$

where
$$k_1 = h f(x_n, y_n)$$
, $k_2 = h f(x_n + \frac{h}{2}, y_n + \frac{k_1}{2})$, $k_3 = h f(x_n + h, y_n + k')$, $k' = h f(x_n + h, y_n + k_1)$

(iv) Runge-Kutta Method of Fourth Order -

$$y_{n+1} = y_n + \frac{1}{6} (k_1 + 2 k_2 + 2 k_3 + k_4)$$

where
$$k_1 = h$$
 $f(x_n, y_n)$, $k_2 = h$ $f(x_n + \frac{h}{2}, y_n + \frac{k_1}{2})$, $k_3 = h$ $f(x_n + \frac{h}{2}, y_n + \frac{k_2}{2})$, $k_4 = h$ $f(x_n + h, y_n + k)$

NUMERICAL APPROACH:

Problem 1. Solve the equation $\frac{dy}{dx} = 1 - y$, y(0) = 0 and find y(0.1), y(0.2), y(0.3).

Solution: The given differential equation is

$$\frac{dy}{dx} = 1 - y$$

$$f(x, y) = 1 - y$$

Taking h = 0.1, we have

$$x_0 = 0$$
, $x_1 = 0.1$, $x_2 = 0.2$, $x_3 = 0.3$

The solution of this problem-

Table 1.1 (Exact Solution)

X	Exact Solution
0.1	0.095163
0.2	0.181269
0.3	0.259182

Table 1.2 (Euler's Method)

X	Euler's Method
0.1	0.1
0.2	0.19
0.3	0.271

Table 1.3 (Modified Euler's Method)

X	Euler's Modified Method
0.1	0.095238
0.2	0.181405
0.3	0.259366

Table 1.4 (Picard's Method)

X	Picard's Method
0.1	0.095167
0.2	0.181333
0.3	0.2595

Runge - Kutta Method -

R-K Method of 1st Order-

Euler method is the Runge – Kutta method of first order.

Table 1.5 (R-K Method of 2nd Order)

X	R-K Method of 2 nd Order
0.1	0.095
0.2	0.180975
0.3	0.258783

Table 1.6 (R-K Method of 3rd Order)

X	R-K Method of 3 rd Order
0.1	0.095167
0.2	0.181277
0.3	0.259192

Table 1.7 (R-K Method of 4th Order)

X	R-K Method of 4 th Order
0.1	0.095163
0.2	0.181269
0.3	0.259182

The values tabulated -

Table 1.8

X	Exact	Euler's/R-	Euler's	Picard's	R-K 2 nd	R-K 3 rd	R-K 4 th
	Solution	K 1 st	Modified	Method	Order	Order	Order
		Order	Method		Method	Method	Method
		Method					
0.1	0.095163	0.1	0.095238	0.1	0.095	0.095167	0.095163
0.2	0.181269	0.19	0.181405	0.18	0.180975	0.181277	0.181269
0.3	0.259182	0.271	0.259366	0.2595	0.258783	0.259192	0.259182

Difference Table:

Difference =
$$|$$
 Exact Solution - Numerical Solution $|$ = $|$ E_n - N_n $|$, n = 1, 2, 3

where numerical solution are Euler's method, Modified Euler's method, Picard's method respectively.

Table 1.9

X	Exact Solution	R-K 1 st Order	Difference	Modified Method	Difference	Picard's Method	Difference	R-K 2 nd order method	Difference	R-K 3 rd order method	Difference	R-K 4 th order method	Differe nce
		Method											
0.1	0.095163	0.1	0.004837	0.095238	0.000077	0.1	0.000004	0.095	0.000163	0.095167	0.000004	0.095163	0
0.2	0.181269	0.19	0.008731	0.181405	0.000141	0.18	0.000064	0.180975	0.000294	0.181277	0.000008	0.181269	0
0.3	0.259182	0.271	0.011818	0.259366	0.000188	0.2595	0.000318	0.258783	0.000399	0.259192	0.000001	0.259182	0

Problem 2. Solve the equation $\frac{dy}{dx} + \frac{y}{10} = e^{\frac{-x}{10}} \cos x$, y(0) = 0 and find y(0.5), y(1), y(1.5).

Solution: The given differential equation is

$$\frac{dy}{dx} + \frac{y}{10} = e^{\frac{-x}{10}} \cos x$$

$$f(x, y) = e^{\frac{-x}{10}} \cos x - \frac{y}{10}$$

Taking h = 0.5, we have

$$x_0 = 0$$
, $x_1 = 0.5$, $x_2 = 1$, $x_3 = 1.5$

The Solution of this problem-

Table 2.1 (Exact Solution)

X	Exact Solution
0.5	0.008301
1	0.015792
1.5	0.022531

Table 2.2 (Euler's Method)

X	Euler's Method
0.5	0.5
1	0.950597
1.5	1.355417

Table 2.3 (Euler's Modified Method)

X	Euler's Modified Method
0.5	0.475901
1	0.905343
1.5	1.291695

Table 2.4 (Picard's Method)

X	Picard's Method
0.5	0.009199
1	0.016648
1.5	0.023347

Runge - Kutta Method -

Runge - Kutta Method of First Order-

Euler method is the Runge – Kutta method of first order

Table 2.5 (R-K Method of 2nd Order)

X	R-K Method of 2 nd Order				
0.5	0.475299				
1	0.428913				
1.5	0.837937				

Table 2.6 (R-K Method of 3rd Order)

X	R-K Method of 3 rd Order				
0.5	0.475611				
1	0.904796				
1.5	1.290921				

Table 2.7 (R-K Method of 4th Order)

X	R-K Method of 4th Order
0.5	0.475609
1	0.904792
1.5	1.290915

The values tabulated -

Table 2.8

X	Exact	Euler's/R-	Euler's	Picard's	R-K 2 nd	R-K 3 rd	R-K 4 th
	Solution	K 1 st	Modified	method	order	order	order
		order	method		method	method	method
		method					
0.5	0.008301	0.5	0.927703	0.009199	0.475299	0.475611	0.475609
1	0.015792	0.950597	0.905343	0.016648	0.428913	0.904796	0.904792
1.5	0.022531	1.355417	1.291695	0.023347	0.837973	1.290921	1.290915

Difference Table:

$$\begin{aligned} \text{Difference} &= \big| \text{ Exact Solution - Numerical Solution } \big| \\ &= \big| \text{ E}_n \text{ - N}_n \, \big| \text{ , n = 1, 2, 3} \end{aligned}$$

where numerical solution are Euler's method, Modified Euler's method, Picard's method respectively.

Table 2.9

X	Exact Solution	Euler's/ R-K 1 st Order Method	Difference	Euler's Modified Method	Difference	Picard's Method	Difference	R-K 2 nd order method	Difference	R-K 3 rd order method	Difference	R-K 4 th order method	Diffe rence
0.5	0.008301	0.5	0.491699	0.475901	0.4676	0.009199	0.000898	0.450597	0.442296	0.475611	0.46731	0.475609	0.467 308
1	0.015792	0.950597	0.934805	0.905357	0.889565	0.016648	0.000856	0.428913	0.413121	0.904796	0.889004	0.904792	0.889
1.5	0.022531	1.355417	1.332886	1.291695	1.269164	0.023347	0.000816	0.837973	0.815442	1.290921	1.26839	1.290915	1.268 384

CONCLUSION:

This paper focused on comparative study on among various numerical method's like Euler's Method, Euler's Modified Method, Picard's and Runge-Kutta Method by numerical approach. In problem 1 we notice table 1.9 the difference is zero by fact Runge-Kutta Method of order fourth is more accurate. By problem 2 we notice table 2.9 the difference is very close to exact value. So Picard's Method is also more accurate method further more, the accurate numerical solution is also depend on the type of function. For example, problem 1 is an algebraic function and problem 2 has exponential and trigonometric function.

REFERENCES

- 1. Islam, Md. A. (2015) A Comparative Study on Numerical Solutions of Initial Value Problems (IVP) for Ordinary Differential Equations (ODE) with Euler & Runge-Kutta Methods. American Journal of Mathematics, 5, 393-404.
- 2. Revathi G. (2017) Numerical Solution of Ordinary Differential Equations and Applications. International Journal of Management & Applied Science, 3(2), 1-5, ISSN: 2394-7926,
- 3. Uddin, M. (2011) Study on Different Numerical Methods for Solving Differential Equations. ResearchGate, DOI: 10:13140/RG.2.2.35517.67048.
- 4. Anidu et al (2015) Dynamic Computation of Runge-Kutta's Fourth-Order Algorithm for First and Second Order Ordinary Differential Equation using Java, 12(3), 211-218.
- 5. Grewal, Numerical Methods, Khanna Publications, 9th edition, 290-316.
- 6. Jain et al, Numerical Analysis, Jeevansons publications, 9(2015), ISBN NO: 978-93-80896-34-2.
- 7. Kalavathy, S. Numerical Methods, 2004, pp.OD.31-OD34, ISBN: 981-254-286-8
- 8. https://www.math.purduc.edu/files/academic/courses/2010spring/MA2620/1-10.pdf

References:

- 5. Islam, Md. A. (2015) A Comparative Study on Numerical Solutions of Initial Value Problems (IVP) for Ordinary Differential Equations (ODE) with Euler & Runge-Kutta Methods. American Journal of Mathematics, 5, 393-404.
- 6. Uddin, M. (2011) Study on Different Numerical Methods for Solving Differential Equations. ResearchGate, DOI: 10:13140/RG.2.2.35517.67048.
- 3. Grewal, Numerical Methods, Khanna Publications, 9th edition, pp.290-316.
- 4. Jain et al, Numerical Analysis, Jeevansons publications, 9(2015), ISBN NO: 978-93-80896-34-2.
- 5. Kalavathy, S. Numerical Methods, 2004, pp.OD.31-OD34, ISBN: 981-254-286-8
- 6. https://www.math.purduc.edu/files/academic/courses/2010spring/MA2620/1-10.pdf