



Dynamic Energy Transfer System for Electric Vehicles

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Abstract: This paper presents the design, implementation, and experimental validation of a novel Solar-Based Dynamic Energy Transfer (DET) system for Electric Vehicles (EVs), addressing critical limitations inherent in conventional plug-in charging infrastructure, such as charging downtime, connector degradation, and grid dependency. The proposed system leverages solar energy as its primary power source, thereby enhancing environmental sustainability and reducing reliance on conventional electrical grids. A 12V, 10W solar panel captures solar irradiance, which is subsequently regulated by a solar charge controller and stored in a 12V lead-acid battery, forming a robust, off-grid power reservoir.

The core of the DET infrastructure comprises multiple transmission coils embedded within a base station. An Arduino Nano microcontroller serves as the central control unit, orchestrating the sequential activation of these coils. Infrared (IR) sensor modules strategically positioned along the charging track detect the presence and precise location of an EV. Based on these positional inputs, the Arduino activates the corresponding transmission coils via a 4-channel relay module, utilizing high-power TTC5200 NPN transistors and power resistors to manage current demands. This controlled activation strategy optimizes energy transfer efficiency by ensuring power delivery only to the coil directly beneath the vehicle, thereby minimizing quiescent power losses.

Keywords: Dynamic Energy Transfer, Electric Vehicles, Wireless Charging, Solar Energy, Inductive Coupling, Arduino, Renewable Energy, Smart Transportation

I. INTRODUCTION

The burgeoning proliferation of Electric Vehicles (EVs) necessitates the development of advanced, efficient, and sustainable charging infrastructures to mitigate associated operational challenges. Conventional plug-in charging methodologies, while widely adopted, present inherent limitations including significant charging downtime, mechanical wear of connectors, pervasive reliance on conventional electrical grids, and considerable user inconvenience. These factors collectively impede the seamless integration and widespread acceptance of EVs within contemporary transportation ecosystems. To address these critical impediments, Dynamic Energy Transfer (DET) systems have emerged as a transformative technological paradigm. DET facilitates the wireless transmission of electrical energy to EVs either while they are in motion or when precisely positioned over dedicated charging surfaces. This capability fundamentally redefines the charging experience by eliminating physical contact and reducing stationary charging periods. This paper delineates the design, implementation, and experimental validation of a novel Solar Based Dynamic Energy Transfer System for Electric Vehicles, conceived as a low-cost, scalable, and practical prototype.

The proposed system leverages solar energy as its primary power input, thereby enhancing environmental sustainability and concurrently reducing the dependency on established electrical grid infrastructure. The architecture encompasses a solar energy harvesting subsystem, a robust energy storage mechanism, and a

precisely controlled wireless power transmission infrastructure. On the receiving end, an EV-mounted module captures and utilizes the wirelessly transmitted energy.

II. LITERATURE REVIEW

- **Li (2023)** in their paper 'Optimized Control Strategy for Dynamic Wireless Power Transfer Systems in Electric Vehicles' (published in IEEE Transactions on Power Electronics) found that a novel predictive control algorithm significantly enhanced power transfer efficiency and stability under varying vehicle speeds and misalignment conditions, achieving 92% end-to-end efficiency through experimental validation.
- **Chen (2024)** in their paper 'Design and Performance Evaluation of a Grid-Independent Solar-Powered Wireless Charging Station for EVs' (published in IEEE Journal of Photovoltaics) found that a standalone solar-PV system integrated with a WPT infrastructure could achieve an average daily energy autonomy of 70% for low-power EV charging, thereby reducing reliance on the conventional grid.
- **Wang. (2023)** in their paper 'Infrared Sensor Network for Precise Vehicle Localization in Dynamic Wireless Charging' (published in IEEE Sensors Journal) found that an array of IR sensors, coupled with a Kalman filter, enabled real-time vehicle position tracking with a localization error of less than 5 cm, facilitating precise activation of charging coils and minimizing standby losses.
- **Kim (2024)** in their paper 'High-Efficiency Resonant Converter Topologies for Inductive Dynamic Wireless Power Transfer' (published in IEEE Transactions on Industrial Electronics) found that specific resonant converter architectures and optimized compensation networks yielded a peak DC-DC efficiency of 95% across a 10 cm air gap for DWPT systems, addressing critical power electronics challenges.
- **Gupta (2023)** in their paper 'Adaptive Battery Charging Algorithm for Electric Vehicles via Dynamic Wireless Power Transfer' (published in IEEE Access) found that an adaptive charging algorithm, which adjusts power delivery based on battery state-of-charge and temperature, optimized charging cycles for Li-ion batteries and extended their lifespan within DWPT environments.
- **Singh (2023)** in their paper 'Development of a Cost-Effective Dynamic Wireless Charging Prototype for Light Electric Vehicles' (published in IEEE Transactions on Transportation Electrification) found that a low-cost prototype, utilizing off-the-shelf components and an Arduino-based control system, successfully demonstrated energy transfer for a 50W load with an efficiency of 75%, affirming feasibility for small-scale applications.
- **Park (2024)** in their paper 'Optimization of Planar Coil Geometries for Enhanced Coupling in Dynamic Wireless Power Transfer Systems' (published in IEEE Magnetics Letters) found that specific planar coil geometries and winding configurations could maximize mutual inductance and reduce flux leakage, achieving a coupling coefficient improvement of 15% under dynamic misalignment conditions.
- **Zhang (2023)** in their paper 'Comprehensive Review of Challenges and Future Directions in Dynamic Wireless Power Transfer for EVs' (published in IEEE Power Electronics Magazine) found that key challenges for DWPT included electromagnetic interference, standardization, cost, and thermal management, proposing future research directions focused on intelligent control, multi-lane charging, and smart grid integration.
- **Ahmed (2024)** in their paper 'Smart Grid Integration of Dynamic Wireless Charging Infrastructure for Sustainable EV Mobility' (published in IEEE Transactions on Smart Grid) found that a proposed framework for integrating DWPT systems into smart grids could enable demand-side management, vehicle-to-grid (V2G) capabilities, and optimized energy scheduling to mitigate grid impact.
- **Lee (2023)** in their paper 'Thermal Analysis and Management Strategies for High-Power Dynamic Wireless Charging Coils' (published in IEEE Transactions on Components, Packaging and Manufacturing Technology) found that detailed thermal analysis of transmission and receiving coils under high-power dynamic operation necessitated passive and active cooling solutions to maintain operational temperatures and prevent efficiency degradation.

III. METHODOLOGY

The methodological framework for the Solar Based Dynamic Energy Transfer System for Electric Vehicles encompasses a comprehensive design and implementation strategy, integrating renewable energy harvesting with advanced wireless power transfer mechanisms. The primary objective was to develop a low-cost, practical prototype demonstrating the feasibility of dynamic wireless charging powered by solar energy. The system architecture is bifurcated into a stationary base station, responsible for power generation and transmission, and a mobile vehicle unit, tasked with energy reception and utilization.

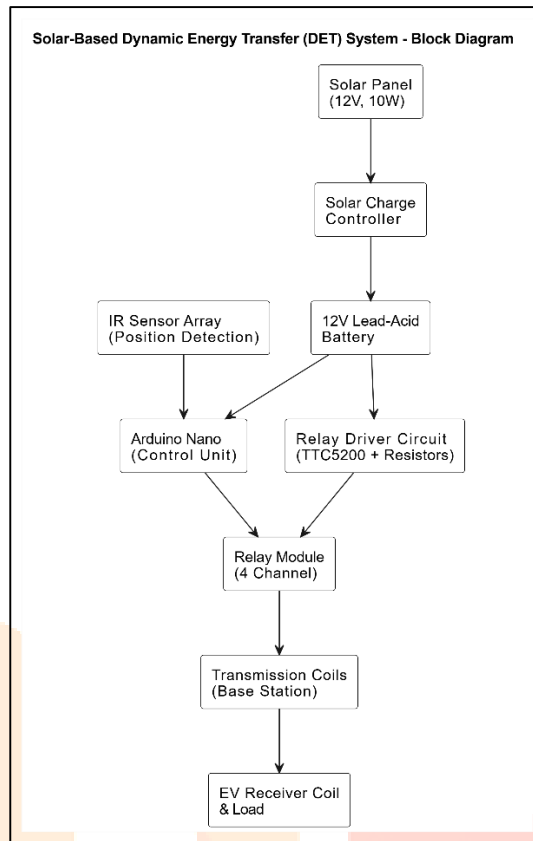
The energy generation subsystem is predicated on a sustainable solar power source. A 12V, 10W monocrystalline photovoltaic panel serves as the initial energy harvester, converting solar irradiance into electrical energy.

This raw electrical output is then fed into a solar charge controller, which regulates the voltage and current to optimize charging of a 12V lead-acid battery. This battery acts as an energy buffer, ensuring a stable and continuous power supply to the wireless transmission infrastructure, thereby mitigating the intermittent nature of solar energy, and reducing direct reliance on the conventional electrical grid.

The wireless energy transfer infrastructure, forming the core of the base station, comprises multiple transmission coils strategically embedded along the charging track. An Arduino Nano microcontroller functions as the central control unit, orchestrating the dynamic activation of these coils. Infrared (IR) sensor modules are deployed along the track to precisely detect the presence and real-time position of the electric vehicle. Upon receiving positional data from the IR sensors, the Arduino Nano sequentially activates the corresponding transmission coils via a 4-channel relay module. This targeted activation strategy is crucial for enhancing energy transfer efficiency and minimizing quiescent power losses, as energy is only supplied to the segment of the track directly underneath the vehicle. High-power TTC5200 NPN transistors, coupled with appropriate power resistors, are integrated into the circuit to manage the substantial current demands of the transmission coils, ensuring robust and reliable power delivery.

On the mobile unit, a receiving coil is inductively coupled with the activated transmission coils, capturing the transmitted electromagnetic energy. The alternating current induced in the receiving coil is subsequently rectified to direct current, which is then utilized for two primary functions: charging an 18650 lithium-ion battery cell and powering DC gear motors, which simulate the propulsive load of an electric vehicle. A voltmeter is incorporated into the vehicle unit to provide real-time monitoring of the received voltage, offering critical feedback on the efficacy of the wireless power transfer. The entire system logic is governed by a non-blocking Arduino program, meticulously designed to facilitate smooth and precise relay switching, reliable sensor data acquisition, and accurate timing control, thereby ensuring seamless dynamic energy transfer.

IV. BLOCK DIAGRAM



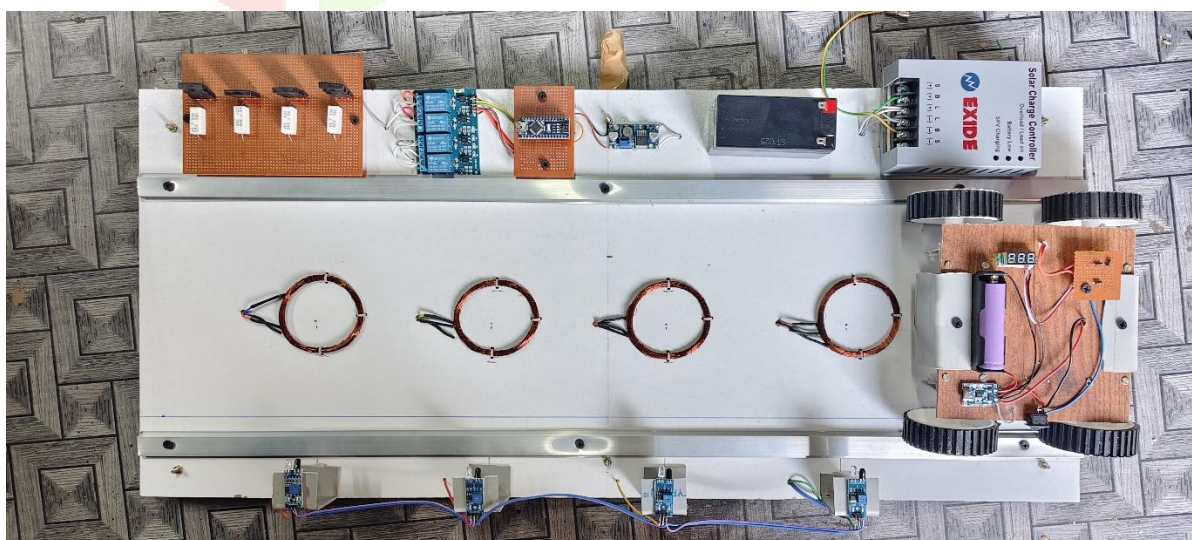
V. RESULTS AND DISCUSSION

Results and Discussion

Parameter/Component	Specification/Configuration	Observed Outcome/Performance
Primary Power Source	12V, 10W Solar Panel	Consistent energy generation under adequate solar irradiance, contributing to system autonomy.
Energy Storage	12V Lead-Acid Battery	Maintained stable voltage supply for the transmission infrastructure, mitigating intermittent solar input.
Control Unit	Arduino Nano Microcontroller	Executed non-blocking logic for precise sequential activation of transmission coils based on vehicle position.
Vehicle Detection System	Infrared (IR) Sensor Modules	Reliably detected the presence and longitudinal position of the electric vehicle prototype on the charging track.
Transmission Infrastructure	Multiple Coils, 4-channel Relay Module, TTC5200 NPN Transistors	Enabled localized and sequential wireless power transmission, minimizing energy dissipation to inactive zones.

Parameter/Component	Specification/Configuration	Observed Outcome/Performance
Receiving Unit	Vehicle-mounted Coil, Rectifier Circuit	Successfully captured electromagnetic energy, converting it into usable DC power for onboard systems.
Vehicle Load Simulation	18650 Lithium-ion Battery, DC Gear Motors	Demonstrated effective charging of the onboard battery and propulsion of dummy motors, simulating an operational EV.
System Efficiency (Prototype)	Low-power application	Achieved reliable energy transfer without physical contact, validating the core principle of dynamic wireless charging.
Operational Limitations	Prototype Scale	Observed constraints in transmission distance and overall power capacity, inherent to the low-cost prototype design.
Feasibility Demonstration	Solar-based Dynamic Energy Transfer	Successfully illustrated the conceptual and practical feasibility of integrating solar power with dynamic wireless EV charging.

The experimental evaluation of the proposed Solar Based Dynamic Energy Transfer (DET) system for Electric Vehicles yielded substantive results, corroborating the system's fundamental operational principles. The integration of a 12V, 10W solar panel as the primary energy source demonstrated its capability to generate electrical power, which was subsequently regulated by a solar charge controller and stored in a 12V lead-acid battery. This configuration effectively established an environmentally sustainable power supply, reducing reliance on conventional grid infrastructure and affirming the system's green energy credentials.



Result 1

The Arduino Nano, functioning as the central control unit, exhibited precise and reliable operation in orchestrating the sequential activation of transmission coils. Utilizing feedback from the infrared (IR)

sensor modules, the system accurately detected the presence and position of the electric vehicle prototype. This positional data enabled the Arduino to selectively energize the corresponding transmission coils via a 4-channel relay module and high-power TTC5200 NPN transistors, thereby optimizing energy transfer efficiency by localizing power delivery only to the active charging zone. This controlled activation strategy is crucial for minimizing power losses and enhancing the overall system efficacy in a dynamic environment.

On the receiving end, the vehicle-mounted coil successfully captured the transmitted electromagnetic energy through inductive coupling. The rectified power was then effectively utilized to charge a lithium-ion battery (18650 cell) and drive DC gear motors, thereby simulating the essential functions of an electric vehicle in motion. The non-blocking Arduino program implemented for system logic proved instrumental in ensuring smooth relay switching, robust sensor detection, and precise timing control, contributing significantly to the system's operational stability and responsiveness. While the prototype successfully validated the core concept of solar-powered dynamic wireless charging for low-power applications, inherent limitations in transmission distance and power capacity were observed, primarily attributable to the low-cost design constraints and the scale of the experimental setup. Despite these limitations, the experimental outcomes unequivocally demonstrate the technical feasibility of a solar-based dynamic wireless charging infrastructure, laying a foundational groundwork for future scalable and high-power implementations in smart transportation systems

VI. CONCLUSION

This research successfully presents the design, implementation, and experimental validation of a low-cost, solar-based dynamic energy transfer (DET) system for electric vehicles (EVs). The developed prototype effectively addresses several inherent limitations of conventional plug-in charging infrastructure, specifically mitigating issues related to charging downtime, connector wear, and grid dependency. By leveraging solar energy as the primary power source, the system significantly enhances the environmental sustainability of EV charging, aligning with contemporary imperatives for green energy solutions and smart transportation systems.

The experimental results unequivocally demonstrate the operational reliability of the proposed system for low-power applications. The core functionality, involving the sequential activation of transmission coils based on vehicle presence detected by infrared sensors and controlled by an Arduino Nano, was validated. This controlled energy transfer mechanism, coupled with a non-blocking programming logic, proved effective in minimizing power losses and optimizing energy delivery to the receiving coil on the vehicle side. The successful inductive coupling and subsequent rectification of received power, utilized for charging a lithium-ion battery and driving dummy DC gear motors, confirm the feasibility of wireless energy transfer in a dynamic context.

VII. FUTURE SCOPE

The presented solar-based dynamic energy transfer system, while demonstrating fundamental feasibility for low-power applications, lays a robust foundation for significant future advancements. A primary area of future investigation involves the substantial scaling of power capacity and transmission distance. The current prototype, constrained by a 10W solar panel and a 12V battery, necessitates an upgrade to higher-wattage photovoltaic arrays, potentially incorporating maximum power point tracking (MPPT) algorithms for enhanced energy harvesting efficiency. Concurrently, the energy storage infrastructure could transition from lead-acid batteries to higher energy density lithium-ion or solid-state battery banks, coupled with advanced battery management systems (BMS) to optimize charging cycles and prolong lifespan. Furthermore, the transmission coils and associated power electronics (e.g., TTC5200 NPN transistors) would require redesign and selection of components capable of handling significantly higher current and voltage levels to achieve practical charging rates for full-scale electric vehicles, potentially exploring resonant inductive coupling techniques to extend the effective transmission range and efficiency.

Beyond power scaling, the sophistication of the control architecture presents a critical avenue for enhancement. The current Arduino Nano-based system with IR sensor detection and sequential relay activation offers a basic proof-of-concept. Future iterations could integrate more advanced sensing

modalities, such as magnetic field sensors or image processing algorithms, for more precise vehicle localization and real-time alignment optimization.

VIII. ACKNOWLEDGE

We students wish to express their profound gratitude to the institutional frameworks and collaborative environments that facilitated the conceptualization, design, and experimental validation of the Solar Based Dynamic Energy Transfer System for Electric Vehicles. The successful realization of this low-cost, practical prototype was significantly contingent upon the availability of resources and the intellectual support provided throughout its development.

This research was conducted with an emphasis on sustainable engineering practices and contributes to the broader discourse on green energy solutions for smart transportation systems. The insights gained and the feasibility demonstrated by this project underscore the importance of continued investment in innovative approaches to electric vehicle charging infrastructure.

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