Design Of Positive Output Boost Converter With Integration Of Buck Converter For Reliable Electric Vehicle Battery Charging Application

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Abstract—DC-DC converters are essential to the use of electric vehicles (EVs). These days, EVs need a different DC-DC converter to charge their high- and low-voltage batteries. The performance of EVs may be impacted by these variables, which have also increased output voltage ripples, switching, and device conduction losses. Furthermore, the prior multiport EV applications, converters feature a greater number of switching and energy storage components. This article suggests a multiport DC–DC converter EV charging circuit to address these problems. The suggested circuit is a single-input dual-output (SIDO) design that combines a buck converter integration with a positive output boost converter (POBCIBC). In this case, the voltage is stepped down using a buck converter and stepped up using a POBC. A basic structure made up of Cascaded Boost Super Lift Luo Converters is called the POBC. The POBCIBC design offers a number of benefits compared to the current multiport converters, such as less storage components, a compact construction, high-voltage transfer gain, proficient efficiency, decreased switching and conduction losses, and reduced output voltage ripples. By building the MATLAB/Simulink and prototype models, the POBCIBC’s performance is evaluated under various operating situations. Various output voltage levels have been created by the suggested converter according to variations in their duty cycles. The findings are displayed to demonstrate the EV application’s proficient POBCIBC.

Index Terms—DC-DC Converter, voltage gain, single input dual output

I. INTRODUCTION

Because they reduce emissions and rely less on fossil fuels, electric vehicles (EVs) can be extremely helpful in the global fight against climate change. The principal elements of electric vehicles (EVs) include the battery, control unit, DC-DC converters, inverter, electrical equipment, and battery management system (BMS). In addition to raising the high voltage from low-voltage renewable energy sources, the DC-DC converter is utilized to charge the battery in electric vehicles [1, 2]. Nevertheless, the low- and high-voltage batteries in current EVs were charged using separate DC-DC converters, which can lead to higher switching losses, more output voltage ripples, significant conduction losses, and a decline in system efficiency. The EVs’ performance is impacted by these problems. This article presents a single-input and multi output (SIMO) DC–DC converter for EVs as a solution to these problems. Favorable outcome in this article, a SIMO converter is defined as a put boost converter (POBC) with integrated buck converter (POBCIBC) operating in continuous conduction mode (CCM) with variable duty cycles. In this article, low voltage is handled by a stepping down converter and high voltage is handled by a POBC. In terms of voltage transfer gain (VTG), tenacity, and ripple voltage, the POBCIBC performs better than the current multiport DC-DC converters used for EV battery charging [3, 4]. The Luo converter for EV use, which integrates a buck converter, is well-done[5]. But this converter’s effectiveness has generated 94.2 percentage. Well-presented is the brush less DC motor drive for EV that is powered by a DC–DC converter at low power levels [6]. For this task, the converter’s efficiency is low, though. These days, multi-input and multi-output (MIMO) DC-DC converters are all the rage in electric vehicles. A well-executed SIMO transformer-based DC–DC converter with variable output voltage is [8]. Nevertheless, this converter had a number of problems that might have decreased its efficiency, including a large transformer size, increased cost, a greater number of power switches, larger on-off losses, and a complex control and driving circuit. A well-presented SIMO
with a connected inductor is [9]. A SIMO converter based on soft switching has been documented in [10]. But as a result of these experiments, coupled inductor s have increased leakage current, increased on-off losses, and necessitated more intricate design procedures. A thorough analysis of the improved buck-boost DC-DC converter has been conducted [11]. This article claims that the converter’s three switches, which use hard switching techniques to calculate the lower and maximum surge inductor currents, are designed for small power applications. There has been extensive reporting on the design of sliding mode controllers (SMC) for multi phase charger and discharge bidirectional DC–DC converters [12].

According to this experiment, during load changes, the inductor current of this converter with this control has resulted in peak overshoots of 1 V and ripple currents of 1.58 A. Additionally, the converter’s design features a more intricate construction and only charges one battery. For low-voltage battery charging in electric vehicles, the zero voltage switching (ZVS) DC–DC converter with IC UCC389 control is well-presented [13]. Nevertheless, the intended converter resulted in 20 W of conduction losses when charging a single battery with a complicated structure. In addition, because of the higher power losses, phase shifter integrated circuits are quite expensive. A thorough examination of a five-stage DC–DC boost converter With a series LC for electric vehicle in real time is provided [14]. Nonetheless, this converter contains eight diodes and ten capacitors in addition to one inductor as storage components. Likewise, this converter’s output voltage has produced peak overshoots of 34.9 percent and a 100 ms settling period. The specifications of several DC-DC converters have been documented in [15], along with an evaluation of their performance and control strategies for EVs. converter has moderately efficiently charged one battery. There has been discussion on the Super Lift Luo Converter with buck converter integration for EV [17]. However, using two switches, two inductors, three capacitors, and three diodes, this converter has generated a 98 percent efficiency.

The thorough comparison of the suggested POBCIBC with earlier converters research gaps for EV applications is shown in Table 1. These studies clearly show that, in comparison to the current converters, the suggested POBCIBC obtained efficiency of 99.39 percent with the fewest amount of elements. The literature analysis indicates that no POBCIBC design with duty cycle control has been documented for use in EV battery charging applications. Therefore, the goal of this article is to design the POBCIBC for use in electric vehicles. By creating the prototype and MATLAB/Simulink models, the entire model is validated under various working situations. The primary goals of this paper follows: (i) The duty is first determined, followed by the VTG and design equations for the POBCIBC’s component parts.

(ii) The converter’s cycles are adjusted to produce a broad variety of controlled output voltages. Next, by building the Simulink and experimental models, the POBCIBC is evaluated at various duty cycles and load resistance changes.

(iii) Lastly, the efficiency study at various converter parameter modifications, output voltage ripples, and time domain specification have all been used to analyze the results of the suggested converter. The structure of this article is as follows: The introduction, literature review, and primary goals of this work are covered in Section 1. The functioning and mathematical VTG of POBCIBC are covered in Sections 2 and 3. Section 4 outlines the suggested formulae for converter component designs. The computation of efficiency is carried out in Section 5. The findings and discussions of POBCIBC under various operating conditions are presented in Section 5. In Section 6, conclusions and upcoming projects are listed.

II. PROPOSED POBCIBC WORKING

In Figure 1, the POBCIBC for EV application is shown. It consists of the input voltage $V_{in}$, two MOSFET switches S1, S2, and storage elements including power transfer diodes D1, D2, load resistors R01, R02, and inductors L1, L2, and capacitors C01, C02. The POBCIBC’s primary features are its single input and two output voltages at various levels. This POBCIBC is better suited as a power supply for different EV components. The POBCIBC’s low-output voltage ($V_{o2}$)

![Fig. 1. Structure of the proposed POBCIBC](image)

![Fig. 2. (a) Modes 1 and 3](image)

![Fig. 3. (b) Mode 2](image)
can be produced with the aid of a buck converter, but its output voltage (Vo1) has been enhanced with the use of a boost converter. POBCiB has excellent In combination with conventional multiport converters, KY converters, and SEPIC, VTG offers reduced circuit components, low current and voltage ripples, a simple structure, good power density, and efficiency. The POBCiB operates in four distinct modes, each of which is represented by an equivalent circuit in Figure 2(a)–2(c). Referring to Figure 2(a), Mode 1 (0 ; t ; t1): S1 is closed and S2 is open when operating in Mode 1. In order to energize inductor L2 in this mode and supply the buck load Ro2, the stored energy from inductor L1’s prior mode is de-energized. This mode ends following the (d1-d2/2)Ts, interval of time. Because of the resonance path between the L1, L2, and Co2 during the previous switching state time interval, the S1 voltage is zero. In addition, the D1 and D2 are operating in reverse polarization.

\[ V_{S1/S2/D1/D2-stress} = V_{o1} - V_{in} \]  

(1)

(2) Check out Mode 2 (t1 ; t ; t2) in Figure 2(b): S1 is open and S2 is closed when operating in Mode 2. To load Ro2, the inductor L2 releases its stored energy. Vin also provides L1 with energy. In this mode, the D2 is inversely polarized. This mode’s time interval is d2Ts time interval.

\[ i_{s1/s2-stress} = i_{in} \]

\[ i_{o1-stress} = i_{o1} \]

\[ i_{o2-stress} = i_{o2} \]  

(2)

Referring to Figure 2(a), Mode 3 (t2 ; t ; t3): This mode operates in the same way as Mode 1. Referring to Figure 2(c): Mode 4 (t3 ; t ; t4): S1 and S2 are in open states in this mode. Energy from L1 and L2 is released to power Ro1 and Ro2 loads.

\[ V_{o1} = V_{in} - V_{L1} \]

\[ V_{o2} = -V_{L2} \]

\[ i_{L1} = i_{co1} + V_{o1}/R_{o1} \]  

(3)

III. Efficiency Computation

When determining the converter efficiency, the element losses are taken into account. Equation is how it is written.

\[ \eta = P_o/(P_o + P_{losses}) \]  

(4)

Next, we can express the converter’s overall power losses using Equation

\[ P_{losses} = P_{switches} + P_{diodes} + P_{capacitors} + P_{inductors} \]

(5)

The switching power losses are calculated during on and off conditions.

\[ P_{switches} = P_{S_1-on} + P_{S_2-off} \]  

(6)

The switching power losses in on/off operating conditions are evaluated.

\[ P_{S1-on} = \frac{1}{2} \int_{0}^{t_0} \frac{h}{d} \left( \frac{1}{d} + i \right) \]

\[ P_{S2-off} = f_{S-off} \sqrt{\frac{i_2}{d_2}} \]

(7)

Diode conduction and non conduction state losses are calculated with help of Equations

\[ P_{D1-on} = \frac{1}{2} \int_{0}^{t_0} \left( 1 - d_1 \right) \]

\[ P_{D1-off} = V_f i_{in} \left( 1 - d_1 \right) \]

(8)

where rf is diode forward resistance and Vf is threshold or forward voltage of the diode.

Total diode losses, \( P_{diodes} = P_{D1-on} + P_{D1-off} \)  

(9)

Storage elements power losses are computed by using Equations

IV. Results and Discussions

The computational and experimental responses of the POB-CiB for EV applications at different load operating circumstances are described in this section along with the corresponding specifications. Table 2’s converter catalog. The specifications of the D1, D2-UF5803, inductors, L1, L2-Ferrite core (10 6832 driver circuit. The gate and source of switches S1 and S2 are then connected to the driver IC outputs in order to control the output voltages with various duty cycles. The experimental
and simulated responses of the output voltages, Vin, and PWM pulses of the proposed POBCIBC with duty cycles of switches d1=60\% and d2=30\%. With minor overshoots and a short setting time of 0.001 s, it is evident from these statistics that the POBCIBC output voltages, Vol=17.14 V and Vo2=5.14 V, match theoretical values (see Table 2). Furthermore, output voltages of the suggested POBCIBC with d1=90\% and d2=80\% are displayed in Figures 7(a) and 7(b). Voltages, PWM pulses, and input voltage of the suggested POBCIBC with d1=90\% and d2=80\% are displayed in Figures 6(a) and 6(b). With minor overshoots and a short setting time of 0.001 s, it is evident from these statistics that the POBCIBC output voltages, Vol=17.14 V and Vo2=5.14 V, match theoretical values (see Table 2). Furthermore, output voltages of the suggested POBCIBC have Vol=60 V and Vo2=6 V, low overshoots, and a setting time of 0.02 s in both the experimental and simulation responses. Moreover, the simulation and experimental analyses of the suggested converter’s Vo1 and Vo2 have shown minimal ripples. The actual and simulation results closely align with the theoretical values (Table 2), capacitors, Co1, Co2, and a 12.5 \text{m} ohm resistance. It is found that the voltage across the switches, current through the switches/inductors/diodes responses with Vin=12 V and d1=60\% and d2=30\% at different load resistance. It is found that the voltage across the switches, current through the switches, inductor, and diodes of the designed POBCIBC has no voltage and current stresses during the converter operation. When the inductor currents remained constant, the POBCIBC was also running in continuous conduction mode (DCM) or continuous CCM. The theoretical key waveforms are represented by all of the parameters (see Figures 3 and 8). Both the theoretical and experimental numerical values for POBCIBC at rated load circumstances are shown in Table 3. These results demonstrate that the suggested POBCIBC has created minimal ripples of the output voltages (1.2 V (simulation), 1.6 V (experimental), and 0.005 V (simulation), 0.0007 V, and efficiency of 99.39\% (simulation) and 98.24\% (experimental) at load of Ro1=25 and Ro2=12.5 \text{m}. The suggested POBCIBC for EV applications using earlier converters. These studies clearly show that, compared to the current converters, the suggested POBCIBC obtained an efficiency of 99.39\% with the fewest amount of components (see Table 3, bolded). Equations (14)–(25) are
used in Figure 9 to display the percentages of loss breakdown at almost full load for the different POBCIBC components. Consequently, semiconductor device losses account for the majority of power losses. It should be mentioned that the switches’ and diodes conduction losses becomes dominant because of the large current flowing through them in the output powers and high-voltage gains. Thus, low-on-resistance, high-power semiconductors to be used to raise the converter’s efficiency. Conduction losses becomes dominant because of the large current flowing through them in the output powers and high-voltage gains. Thus, low-on-resistance, high-power semiconductors to be used to raise the converter’s efficiency.

V. CONCLUSION

In this article, the theoretical analysis, design and output voltage regulation of multi port POBCIBC operated in CCM using different duty cycle has been successfully demonstrated. The PWM pulses were generated using PIC18F6410 for POBCIBC. The main merits of the designed POBCIBC over the previous multi port converter as follows: (i) Obtain the good VTG and flexibility to change the different output voltages; (ii) Excellent...
efficiency like 99.39% percent (iii) Minimal output ripple voltages as well as inductor ripple currents; (iv) Simple structure and less number of components; and (v) Low conduction and switching losses. The experimental and simulation results are presented in order to prove the competence of the designed multi port POBCIBC at different load and duty cycle operating conditions. It is, therefore, mainly designed for EV battery charging application. In future, multi port converter based LUO and KY topologies to be built for EV and renewable energy application.

REFERENCES


![Fig. 13.](image-url)