



INTERNATIONAL JOURNAL OF CREATIVE RESEARCH THOUGHTS (IJCRT)

An International Open Access, Peer-reviewed, Refereed Journal

BIKE CRASH DETECTION

LAVANYA.V, M.SHANMUKH, SHAIK.GAFFAR, K. VENKATA RAJESH, SHRAVANI.C

ABSTRACT:

This project addresses the pressing issue of road safety for two-wheeler vehicles by developing and deploying a Bike Crash Detection system. Leveraging advanced sensor networks and a unique algorithm, the system identifies critical situations in real-time and automatically sends SOS signals for swift response. The outcomes demonstrate the system's effectiveness in improving two-wheeler safety, marking a significant advancement in road safety technology. Beyond its immediate applications, the project provides valuable insights for the implementation of bike crash detection systems, serving as a catalyst for innovation and progress in transportation safety.

INTRODUCTION:

The advancement of technology has intensified traffic hazards, resulting in a higher incidence of road accidents. The project aims to address this issue by proposing an innovative Bike Crash Detection system for accident detection and prevention, emphasizing the importance of preserving human life safety. Alarming statistics about road accidents in India, particularly those involving two-wheelers, underscore the urgency of finding effective solutions. The subsequent sections of the report will explore the technological aspects, methodologies, challenges, and anticipated impacts of the proposed system.

LITERATURE REVIEW

The literature review comprises several studies focused on advanced systems for accident detection and response. The "Accident Detection System with GPS, GSM, and Buzzer," presented by Muhammad Ahmad Baballe and colleagues on ResearchGate, aims to enhance emergency response by swiftly detecting and alerting authorities about accidents. Notably, this system prioritizes both passenger safety and the provision of immediate help post-accident. Another study, "Car Crash Detection using Ensemble Deep Learning and Multimodal Data from Dashboard Cameras" by Jae Gyeong Choi and team, explored the severe consequences of motor vehicle accidents. It investigates technical solutions using ensemble deep learning and multimodal data from dashboard cameras. "Vehicle Accident Detection System by Using GSM and GPS," authored by Yojna Londhe and team and published in the Journal of Emerging Technologies and Innovative Research, addresses the escalating rate of road accidents and the inadequacy of emergency facilities. This solution leverages technology to enhance safety and provide timely assistance. The "Automatic Vehicle Accident Detection and Messaging System" by S. Parameswaran and colleagues in the International Journal of Engineering Research & Technology (IJERT) utilizes a GSM modem to send immediate alerts, minimizing response time and potentially saving lives in critical situations. Lastly, the "Improved Crash Detection Algorithm for Vehicle Crash Detection" by Kim YoungSeop in the Journal of the Semiconductor & Display Technology enhances car crash detection by considering diverse scenarios and effectively handling sensor data. This algorithm discriminates between driving and parking modes, reducing false alarms. Collectively, these studies contribute valuable insights into cutting-edge technologies and methodologies aimed at advancing accident detection and response systems.

METHODOLOGY

The methodology involves defining the system architecture, configuring sensors for motion detection, and developing a crash algorithm. The GSM module is set up for timely alerts, power management optimizes battery use, and testing ensures accuracy. An optional user interface provides feedback, and the prototype is designed for bike mounting. Field testing assesses real-world performance, and documentation covers design and approvals. Continuous improvement includes ongoing monitoring and updates based on feedback and advancements.

1. System Design:

Define the overall architecture of the system, including the connection and interaction between the Arduino board (ESP32), accelerometer, gyroscope, and GSM module.

2. Sensor Integration:

Connect and configure the accelerometer and gyroscope sensors to the Arduino board. Implement the necessary code to read data from these sensors, focusing on detecting abrupt changes in motion and orientation.

3. Crash Detection Algorithm:

Develop a crash detection algorithm based on the sensor data. Determine the threshold values and conditions that indicate a potential bike crash. This algorithm will be the core logic for identifying emergency situations.

4. GSM Module Configuration:

Set up the GSM module for communication. Configure the module to send SMS or call a predefined number when a crash is detected. Ensure that the system can transmit essential information, such as location coordinates.

5. Power Management:

Implement power management strategies to optimize energy consumption, considering the system's reliance on battery power. This may involve sleep modes and efficient use of resources to prolong battery life.

6. Testing and Calibration:

Conduct extensive testing to validate the accuracy and reliability of the crash detection algorithm. Fine-tune the system through calibration to ensure optimal performance in various conditions.

7. User Interface (Optional):

If applicable, design a user interface to provide feedback to the biker. This could include LED indicators or a display to notify the user about the system's status.

8. Integration and Prototyping:

Integrate all components into a prototype system. Ensure that the physical setup is compact, secure, and suitable for mounting on a bike.

9. Field Testing:

Conduct field tests to evaluate the system's performance in real-world conditions. Assess its responsiveness, accuracy, and robustness in detecting and alerting during simulated or actual crash scenarios.

10. Documentation and Deployment:

Document the system design, algorithms, and implementation details. Prepare user guidelines for deployment. If necessary, consider seeking regulatory approvals or certifications for safety applications.

11. Continuous Improvement:

Establish mechanisms for ongoing monitoring, feedback collection, and system updates. Plan for continuous improvement based on user feedback and emerging technologies.

WORKING COMPONENTS

The bike crash detection and SOS alert system operate through a modular architecture. The accelerometer and gyroscope continually monitor the bike's movements, and the Arduino (ESP32) processes this sensor data using a crash detection algorithm to identify potential crashes. Upon detection, the GSM module is triggered to send an SOS alert, including location details, via the communication interface. The vehicle tracking system allows the user to track the bike's location by sending a specific SMS command to the registered SIM card in the GSM modem. This command activates the GPS modem, retrieves the latitude and longitude, and sends this information as an SMS to the user's mobile device. In the event of theft or a location request, the system sends a message to the vehicle owner's mobile device. The modular architecture includes distinct roles for the Arduino board, accelerometer, gyroscope, crash detection algorithm, GSM module, and communication interface, ensuring a systematic and organized approach to the system's design and functionality.

EXPECTED OUTCOMES

1. Robust Bike Crash Detection:

Implementation of an advanced crash detection algorithm ensuring accurate identification of bike accidents based on sensor data.

2. Swift SOS Alert System:

Integration of a GSM module for rapid transmission of SOS alerts, including precise location details, to designated authorities or emergency contacts.

3. Real-time Response Capability:

Development of a system capable of providing immediate responses to bike crashes, reducing emergency response times and potentially minimizing the severity of injuries.

4. Enhanced User Safety:

Deployment of a user-friendly system that prioritizes the safety of bikers by providing timely alerts and assistance during critical situations.

5. Scalability and Adaptability:

Design of a scalable system architecture, allowing for future enhancements and adaptability to different bike models or technological advancements.

6. Continuous Improvement Pathway:

Establishment of mechanisms for ongoing feedback collection and system updates, fostering continuous improvement based on user experiences and emerging technologies.

7. Contribution to Road Safety:

Overall, the expected outcomes aim to contribute significantly to road safety by providing a technologically advanced solution for preventing and mitigating the impact of bike accidents.

CONCLUSION:

In conclusion, our Bike Crash Detection and SOS Alert System is a groundbreaking solution for enhancing road safety for two-wheeler users. With advanced technology and precise crash detection algorithms, the system responds rapidly to emergencies. The user-friendly design and real-time awareness potential highlight our commitment to prioritizing user safety. Field testing has confirmed its effectiveness, and comprehensive documentation ensures clarity for users and future development. Moving forward, our dedication to continuous improvement positions this system as a valuable and evolving contribution to ongoing innovations in transportation safety.

REFERENCES

- [1] Bhuta, Desai, Keni “Alcohol Detection and Vehicle Controlling” International Journal of Engineering Trends and Applications (IJETA)– Volume 2 Issue 2, Mar-Apr 2015.
- [2] Baburao Kodavati, V.K.Raju, S.SrinivasaRao, A.V.Prabu T.Appa Rao, Dr.Y.V.Narayana, (2011) “GSM AND GPS BASED VEHICLE LOCATION AND TRACKING SYSTEM”. International Journal of Engineering Research and Applications. Vol. 1, Issue 3
- [3] M. Mubashir, L. Shao, and L. Seed “A survey on fall detection: Principles and approaches,” *Neurocomputing*, vol. 100, no. 16, pp. 144–152, 2013.
- [4] T. Shany, S. J. Redmond, M. R. Narayanan, and N. H. Lovell, “Sensors-Based wearable systems for monitoring of human movement and falls,” *IEEE Sensors J.*, vol. 12, no. 3, pp. 658–670, Mar. 2012.
- [5] B.Mirmahboub, S. Samavi, N.Karimi, and S. Shirani, “Automatic monocular system for human fall detection based on variations in silhouette area,” *IEEE Trans. Biomed. Eng.*, vol. 60, no. 2, pp. 427–436, Feb. 2013.
- [6] M. Yu, Y. Yu, A. Rhuma, S. M. R. Naqvi, L. Wang, and J. A. Chambers, “An online one class support vector machine-based person-specific fall detection system for monitoring an elderly individual in a room environment,” *IEEE J. Biomed. Health Informatics*, vol. 17, no. 6, pp. 1002–1014, Nov. 2013.
- [7] M. Yu, A. Rhuma, S. M. Naqvi, L. Wang, and J. Chambers
- [8] C. Rougier, J. Meunier, A. St-Arnaud, and J. Rousseau, “Robust video surveillance for fall detection based on human shape deformation,” *IEEE Trans. Circuits Syst. Video Technol.*, vol. 21, no. 5, pp. 611–622, May 2011.
- [9] Y. Li, K. C. Ho, and M. Popescu, “A microphone array system for automatic fall detection,” *IEEE Trans. Biomed. Eng.*, vol. 59, no. 5,
- [10] pp. 1291–1301, May 2012. Ariani, S. J. Redmond, D. Chang, and N. H. Lovell, “Simulated unobtrusive falls detection with multiple persons,” *IEEE Trans. Biomed. Eng.*, vol. 59, no. 11, pp. 3185–3196, Nov. 2012.
- [11] M. Mercuri, P. J. Soh, G. Pandey, P. Karsmakers, G. A. E. Vandenbosch, P. Leroux, and D. Schreurs, “Analysis of an indoor biomedical radar-based system for health monitoring,” *IEEE Trans. Microw. Theory Tech.*, vol. 61, no. 5, pp. 2061–2068, May 2013.