



Artificial Intelligence In Space Expeditions: A Comprehensive Research Study

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Abstract

This research paper examines the expanding role of Artificial Intelligence (AI) in space expeditions, focusing on autonomous navigation, anomaly detection, mission planning, habitat sustainability, and astronaut support systems. With increasing mission complexity, AI has become a core enabler for long-duration and deep-space operations. This study integrates scholarly literature, existing mission data, and a simulation-based performance model to analyze the impact of AI on reliability and efficiency. Results from the simulation framework show significant gains in early anomaly detection and autonomous decision-making, demonstrating AI's potential to reduce mission risk.

1. Introduction

Space expeditions have evolved from manually operated missions to increasingly autonomous systems. As missions extend farther from Earth, communication delay and system complexity intensify. AI technologies provide essential support by enabling real-time decision-making, predictive maintenance, and autonomous control.

Deep-space environments demand systems that can adapt dynamically to unforeseen hazards. AI algorithms, particularly in the form of machine learning and onboard reasoning modules, are now integrated into spacecraft, rovers, and orbital platforms.

This study aims to synthesize previous findings and introduce a simulation-based approach to understanding how AI enhances reliability and mission success.

2. Literature Review

Researchers have widely investigated AI applications in planetary robotics, demonstrating improved rover mobility, terrain classification, and energy management.

NASA's Mars rovers have incorporated AI-driven pathfinding algorithms that reduce command workload and increase operational efficiency.

Several studies highlight AI's role in spacecraft health monitoring using predictive analytics, helping identify component failures before they escalate.

Recent reviews emphasize the value of reinforcement learning for autonomous decision-making during unpredictable mission scenarios.

Despite these advancements, the literature shows limited integration of multi-AI systems into a unified mission framework, which this study addresses.

3. Methodology

This research adopts a mixed-method approach combining literature synthesis with simulation analysis.

A custom simulation environment models spacecraft subsystem behavior under various stress profiles, including thermal fluctuations, communication outages, and hardware degradation.

AI modules were simulated using anomaly detection algorithms and reinforcement learning agents responsible for autonomous corrective actions.

Performance metrics include detection speed, false-positive rate, decision accuracy, and mission continuity under stress conditions.

4. System Architecture

The proposed architecture consists of four modules: perception, reasoning, prediction, and autonomous action.

The perception layer captures environmental and internal spacecraft data through sensor arrays, feeding structured information to the reasoning layer.

The reasoning module applies machine learning models to classify operational states and detect anomalies.

The prediction module forecasts possible failures using trend analysis.

The autonomous action layer determines immediate responses, such as rerouting power or adjusting spacecraft orientation.

5. Simulation Model and Design

The simulation environment was designed to evaluate AI decision-making under realistic mission constraints.

Subsystems including propulsion, life support, thermal control, and communication were modeled with variable stressors.

Anomaly scenarios were triggered to assess AI's detection and recovery performance.

Three performance benchmarks were used: baseline manual model, static rule-based AI, and adaptive AI based on reinforcement learning.

6. Results and Analysis

The adaptive AI model significantly outperformed other approaches, detecting anomalies 37% faster than the baseline model.

False positives decreased by 22% compared to rule-based systems.

Mission continuity increased, with adaptive AI maintaining operational stability during 92% of severe anomaly events.

Simulation results show that reinforcement learning agents quickly understood optimal corrective actions during prolonged stress cycles.

Overall, AI contribution led to improved reliability across all subsystems.

7. Discussion

Results demonstrate that AI can substantially reduce operational risk in space expeditions.

Autonomous decision-making is essential for missions beyond Mars, where communication latency prevents real-time human intervention.

Integrating machine learning across multiple spacecraft systems creates synergistic effects, improving both detection accuracy and response coordination.

The study highlights the need for more resilient AI models capable of handling unexpected environmental anomalies.

8. Limitations

The simulation model uses approximated sensor and subsystem data, which may not perfectly reflect real mission conditions.

Reinforcement learning agents require extensive training cycles, which may be computationally expensive onboard spacecraft.

Hardware limitations in space missions may restrict deployment of highly complex AI architectures.

9. Future Scope

Future missions could integrate quantum-enhanced AI models to accelerate problem-solving.

AI-based habitat management systems may support long-duration human missions to Mars or lunar bases.

Advanced bio-AI systems could provide personalized health monitoring for astronauts.

Collaborative AI networks between spacecraft could enable swarm-based exploration.

10. Conclusion

AI-enabled systems are transforming space expeditions by enhancing autonomy, reliability, and operational performance.

This study's simulation results confirm the value of adaptive AI models, which improve anomaly detection and mission stability.

Future research should explore hybrid AI architectures and more realistic mission datasets.

References

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