



# MULTIPLE CAMERA NETWORK

<sup>1</sup>Sushanth Buddhala,<sup>2</sup>Dr.Cherukupalli. Mallikarjuna Rao,<sup>3</sup>Vangeti Sravan Reddy,<sup>4</sup>Ch. Jayanth,<sup>5</sup>P. Sri Ram Charan

<sup>2</sup>CoE, <sup>1,3,4,5</sup>Student

<sup>1,2,3,4,5</sup>Department of Computer Science and Technology

<sup>1,2,3,4,5</sup>Gokaraju Rangaraju Institute of Engineering and Technology, Hyderabad, India

**Abstract:** The Multiple Camera Network (MCN) paradigm revolutionizes visual data capture through strategically positioned interconnected cameras. Deployed in sectors like security, cinematography, and research, MCNs offer panoramic insights. The abstract explores vital MCN components, encompassing synchronization, data fusion, and real-time processing. It sheds light on applications like crowd monitoring, 3D reconstruction, and immersive video production. Despite challenges like calibration and computational needs, the grid-organized MCN excels in synchronized data capture. Surveillance benefits from PTZ and smart cameras, enhancing control and coordination. Object tracking in surveillance hinges on feature extraction and background subtraction, with increasing interest in video surveillance. Embracing edge computing and AI, MCNs gain on-the-fly analysis and predictive modeling. The abstract concludes, highlighting MCNs' adaptability and scalability, positioning them as pivotal in reshaping surveillance and imaging standards from security to entertainment.

## I. INTRODUCTION

In the ever-expanding landscape of technological innovation, the quest for comprehensive and nuanced data acquisition has led to the development of advanced systems that transcend traditional imaging solutions. Among these groundbreaking technologies, the concept of a "Multiple Camera Network" stands out as a powerful paradigm shift in the way we perceive and capture visual information. A Multiple Camera Network is a sophisticated arrangement of interconnected cameras strategically positioned to provide expansive coverage of a given environment. This innovative approach goes beyond the limitations of single-camera systems, offering a panoramic and multi-dimensional view that holds immense potential across various industries and applications. In this introduction, we embark on a journey to explore the transformative capabilities and diverse applications of Multiple Camera Network systems.

From enhancing security and surveillance to revolutionizing computer vision and spatial understanding, these networks promise to redefine the boundaries of visual intelligence. By fusing the outputs of multiple cameras into a unified and cohesive whole, this technology opens new avenues for data analysis, object tracking, and immersive experiences. As we delve deeper into the intricacies of MCN systems, we will unravel the technical components that make these networks formidable tools in the realm of visual data acquisition. From synchronization mechanisms to data fusion algorithms, we will uncover the engineering marvels that enable seamless cooperation among cameras, providing a holistic and real-time perspective. Furthermore, this exploration will extend to the potential challenges and considerations associated with the deployment of MCNs.

Issues such as calibration, data synchronization, and ethical implications will be addressed, highlighting the importance of responsible and mindful integration of this technology into various domains. In essence, this introduction sets the stage for a comprehensive exploration of MCN systems, inviting readers to envision the possibilities that arise when we break free from the constraints of single-lens perspectives. By embracing this advanced imaging paradigm, we embark on a journey towards unlocking a new era of visual intelligence

that promises to reshape industries, redefine research methodologies, and enhance our understanding of the world in ways previously unimaginable.

The capturing of still or moving images is an important step required in object recognition, object behavior analysis, and object monitoring processes. One of the possible methods of capturing an image is with the aid of a camera that could create a single image of an object (i.e., still image) or a sequence of images in rapid succession (i.e., video image). Currently, there are many image acquisition technologies (e.g., cameras). Most of the technologies are built on catadioptric or fisheye cameras, as well as image acquisition systems with static or moving parts. Camera classification or type can be based on one characteristic or another, from the FOV, image sensor, image quality, focusing properties, or power of projection. In this survey, the discussion will be based on unidirectional and omnidirectional cameras. There are six types of cameras considered in this survey; Pan-Tilt-Zoom (PTZ) camera [Fig. 1], smart camera [Fig. 2], orthographic camera [Fig. 3], perspective camera (pinhole) [Fig.4], omnidirectional (panoramic) camera [Fig. 5] and thermal camera [Fig. 6].



Fig. 1. Pan-Tilt-Zoom(PTZ)

Camera



Fig. 2. Smart



Fig. 3.Orthographic Camera

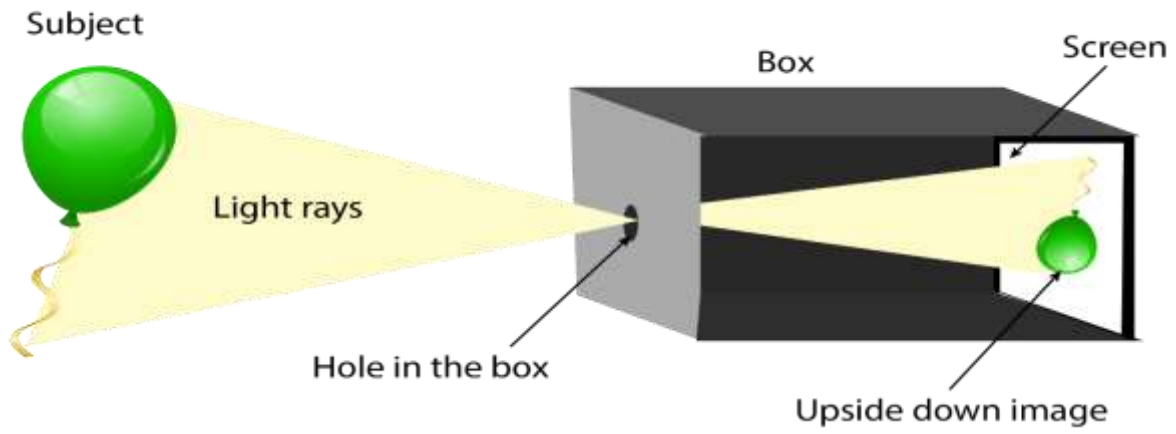


Fig. 4. Perspective Camera



Fig. 5. Omnidirectional (panoramic) Camera



Fig. 6. Thermal Camera

## II.LITERATURE SURVEY

In the surveillance system, the combination of multiple heterogeneous cameras and the discovery of Pan-Tilt-Zoom (PTZ) and smart cameras have brought tremendous achievements in multi-camera control and coordination. Different approaches have been proposed to facilitate effective collaboration and monitoring among the camera network. Furthermore, the application of multi-cameras in sports has made the games more interesting in the aspect of analyses and transparency. The application of the multi-camera system in education has taken education beyond the four walls of the class. The method of teaching, student attendance enrollment, determination of students' attention, teacher and student assessment can now be determined with ease, and all forms of proxy and manipulation in education can be reduced by using a multi-camera system. Besides, the number of cameras featured on smartphones is gaining noticeable recognition. However, most of these cameras serve different purposes, from zooming, telephoto, and wider Field of View (FOV). Therefore, future smartphones should be expecting more cameras or the development would be in a different direction.

The Pan-Tilt-Zoom (PTZ) cameras are usually applied in surveillance-based applications because of their high-resolution image output. They have a dynamic field of view and can be configured to monitor a specified area of coverage. PTZ cameras have the capability of zooming far distant objects to display the detailed information required to analyze a captured image. However, they can only cover a limited area of the scene at one time. Smart cameras are intelligent cameras that came into the limelight around the mid-80s. They have the power of extracting application-based information from a captured image together with creating event information of an image or making an intelligent decision that will be applied in an automated process.

At the earliest time of its invention, there was a limitation in its capabilities in terms of sensitivity and processing power, but later there were great improvements in its capabilities. The orthographic camera captures an image without any perspective distortion. They produce a two-dimensional (2D) image output without any image depth. Perspective cameras are cameras that display an image in a real-world view. They produce a three-dimensional (3D) image with depth. All pinhole cameras are also referred to as perspective cameras. Omni-directional cameras can cover 360 degrees FOV with a high-resolution image of about 1600×1200 pixels. They have the capability of covering images over a wide area FOV. A thermal camera (infrared camera or thermal imager) uses infrared radiation to create an image. It senses infrared light with a wavelength from about 1µm to 14 µm.

A multi-camera system is an arrangement of sets of cameras used in capturing images or sequences of images of a scene. A multi-camera setup can be homogeneous (consist of the same types of camera setup) or heterogeneous (consist of different types of camera setup) that form a multi-camera system. The combination of two or more cameras can be employed to expand the span of the measuring area and when performing a high-precision measurement. The FOV of a multi-camera setup is more than that of the single camera. The advantages of high accuracy, and low cost of visual measurement techniques made the multi-camera system to be widely used in different areas of application. [Fig. 7] shows the coverage area of three heterogeneous camera, which can never be obtained through a single camera

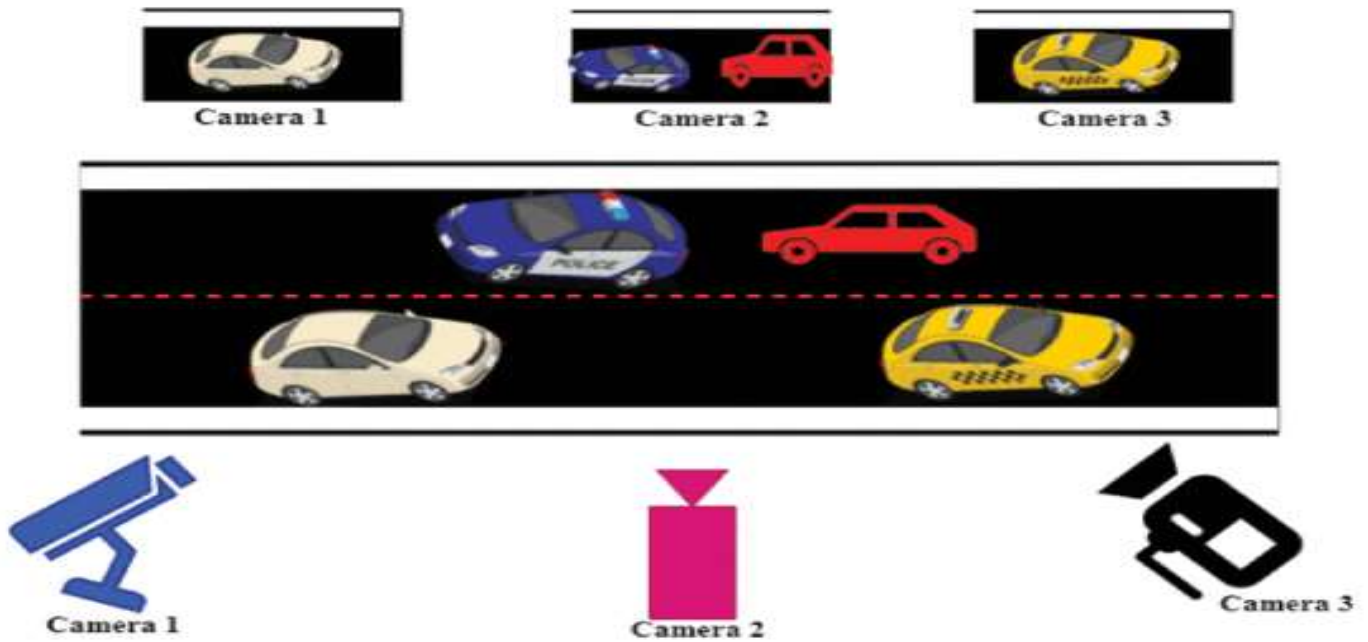


Fig. 7. FOV of multi-camera setup

According to Yilmaz and Mehmood, the omnipresence of high precision and low-cost cameras, with high computational resources, and the quest for automation in video analyses have generated great interest in multi-camera system developments. The awareness of multi-camera started around 1884, where Triboulet used a multi-camera consisting of seven cameras tightened to a balloon (one camera attached to the mouth of the balloon and six others attached to the circumference of the balloon) mainly to perform aerial imaging. Similarly, in the mid-nineteenth century, multi-camera systems were employed in industrial machine automation, where the application of robots took charge of humans in the industry [10]. Since then, the research on multi-camera developments has been expanding. This can be shown by the number of papers on multi-camera applications. To prove this, a search on IEEEXplore was done using the keyword “multi-camera systems”. The result of this search is shown in [Fig. 8]. The figure shows that the number of publications related to the multi-camera system is in the increasing trend, which indicates that research on the multi-camera system is still very popular in the present day.

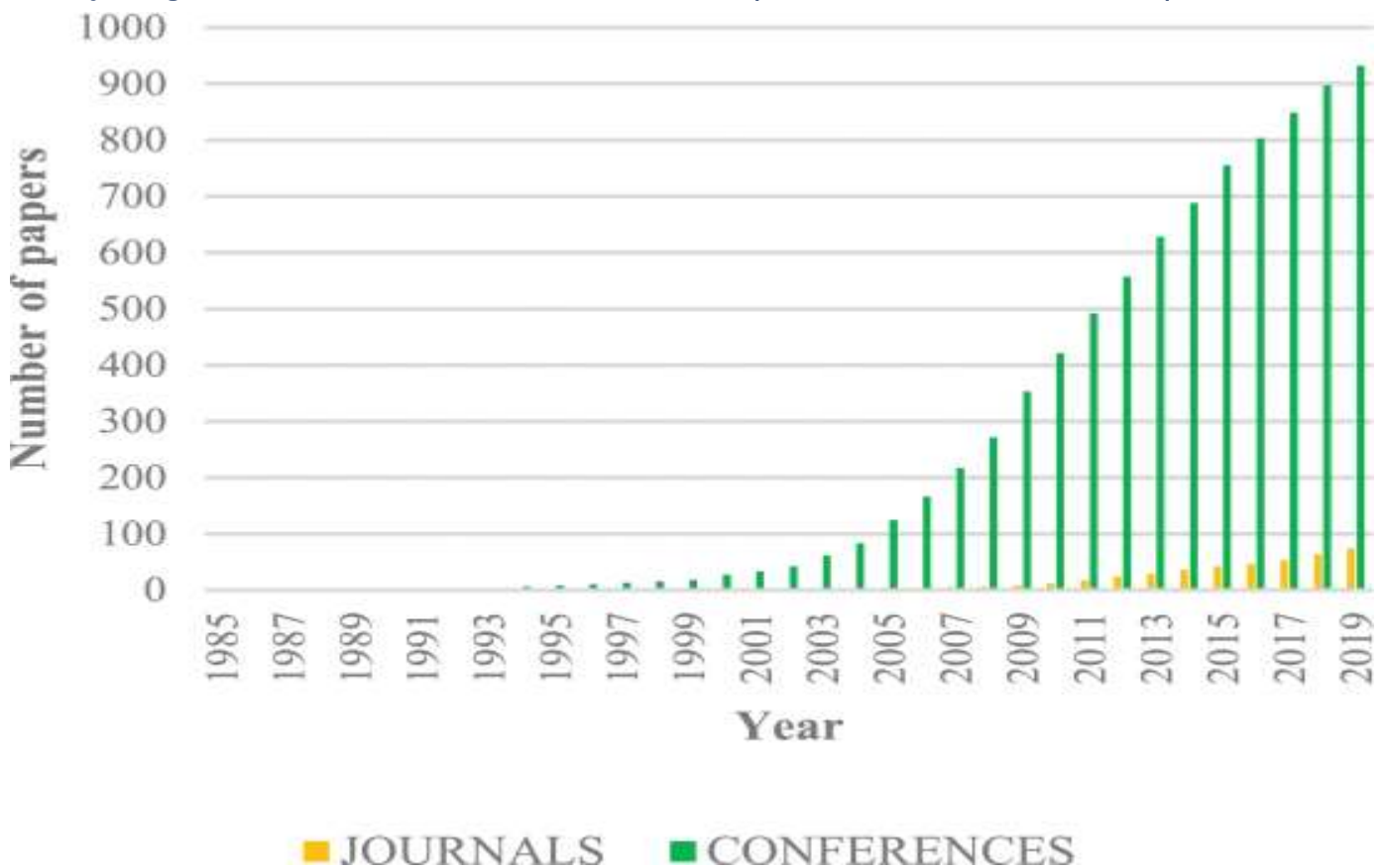


Fig. 8.Graph

Even though several surveys concerning multi-camera systems have been published, virtually all of them focused on a selected aspect of the multi-camera system and particular areas of its applications (e.g., tracking or surveillance). These surveys, of course, do not cover the wide spectrum of multi-camera system studies. Because of the literature shortfall, this survey paper comprehensively covers the multi-camera system in four different areas of application, with emphasis given on the previous works, identifying the problems with the existing strategies, the recent advancements and highlighting the future direction.

### III.RESEARCH METHODOLOGY

#### 3.1 Module Description

Designing a module for Multiple Camera Networks (MCNs) typically involves breaking down the system into distinct components or modules, each serving a specific function or capability.

##### 3.1.1 Camera Management Module (HD Camera Network):

This module is responsible for the configuration, control, and synchronization of all cameras within the network. It ensures that cameras capture data simultaneously or as per predefined schedules.

##### 3.1.2 Data Capture Module (NVR):

The data capture module manages the collection of visual data from all cameras in the MCN. It ensures data integrity, compression, and efficient transmission to storage.

##### 3.1.3 Central Control (Control Center):

The central control hub serves as the core of the MCN, orchestrating camera operations, data management, and communication.

##### 3.1.4 Data Storage and Management Module (Data Monitor):

This module handles the storage and retrieval of visual data captured by the MCN. It ensures data availability, redundancy, and efficient retrieval.

### 3.1.5 Data Processing and Analysis Module (Data Monitor):

The data processing and analysis module is responsible for real-time or post-event analysis of visual data, utilizing computer vision and AI techniques.

### 3.1.6 Communication and Networking Module (IP Network):

This module ensures seamless communication between cameras, the central control hub, and other connected devices.

### 3.1.7 User Interface Module (Display):

The user interface module provides a user-friendly interface for administrators and operators to monitor and control the MCN.

### 3.1.8 Maintenance and Reporting Module:

This module supports system maintenance, health monitoring, and reporting.

### 3.1.9 Integration with External Systems Module (Remote Browser):

If necessary, this module facilitates the integration of the MCN with other systems, such as alarms, sensors, or robotics.

Note: Each of these modules plays a critical role in the overall functionality of the Multiple Camera Network, and their integration ensures the efficient and effective operation of the system for various applications.

## 3.2 UML DIAGRAMS

### 3.2.1 Class Diagram

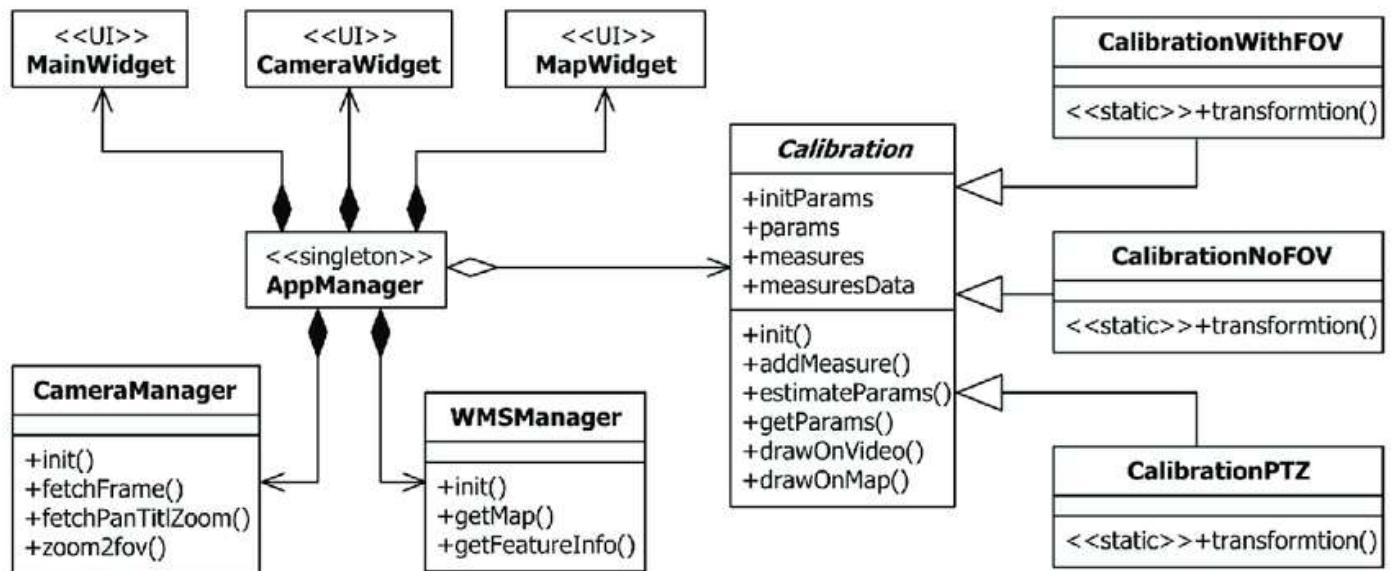


Fig. 9. Class Diagram

### 3.2.2 Data Flow Diagram (Level-0)

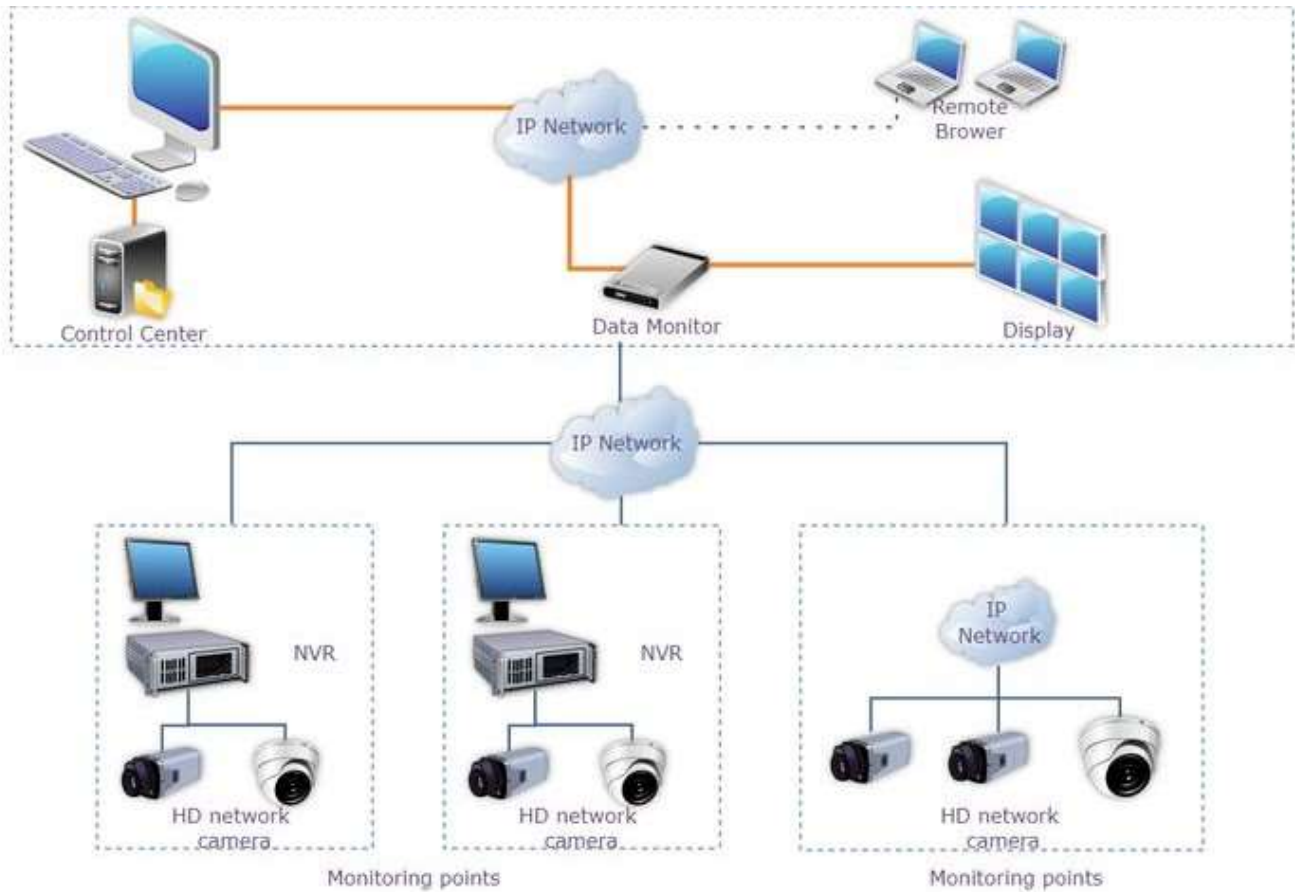


Fig. 10. Data Flow Diagram

## IV.IMPLEMENTATION

### 4.1 Source Code

```

if results.detections:
    for detection in results.detections:
        #cropping out the detected image
        x1=max(0,math.floor((detection.location_data.relative_bounding_box.xmin*width)))
        x2=max(0,math.floor((detection.location_data.relative_bounding_box.xmin+detection.location_data.relative_bounding
        y1=max(0,math.floor((detection.location_data.relative_bounding_box.ymin*height)))
        y2=max(0,math.floor((detection.location_data.relative_bounding_box.ymin+detection.location_data.relative_bounding
        print(x1,x2,y1,y2)
        cropping=image[y1:y2,x1:x2]
        mp_drawing.draw_detection(image, detection)
        ans = DeepFace.analyze(cropping,actions=['emotion'],enforce_detection = False)

        print(ans[0]["dominant_emotion"])
cv2.imshow('MediaPipe Face Detection', image)

if cv2.waitKey(1) & 0xFF == ord('q'):
    break
time.sleep(0.5)

cap.release()

```

Fig. 11. Source Code



```

In [1]: from deepface import DeepFace

In [ ]: import cv2
import mediapipe as mp
mp_face_detection = mp.solutions.face_detection
mp_drawing = mp.solutions.drawing_utils
total=0
import json
import cv2
import time,math
import numpy as np
from IPython.display import clear_output
cap = cv2.VideoCapture(0)

#starting the face detection models
with mp_face_detection.FaceDetection(
    model_selection=1, min_detection_confidence=0.5) as face_detection:
    while cap.isOpened():
        try:
            success, image = cap.read()
            height, width, channels = image.shape
        except:
            break

        if not success:
            print("Ignoring empty camera frame.")
            break

        image.flags.writeable = False
        image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
        results = face_detection.process(image)
        image.flags.writeable = True
        image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)
        x=0
        if results.detections:
            for detection in results.detections:

```

Fig. 12. Source Code

## 4.2 Execution

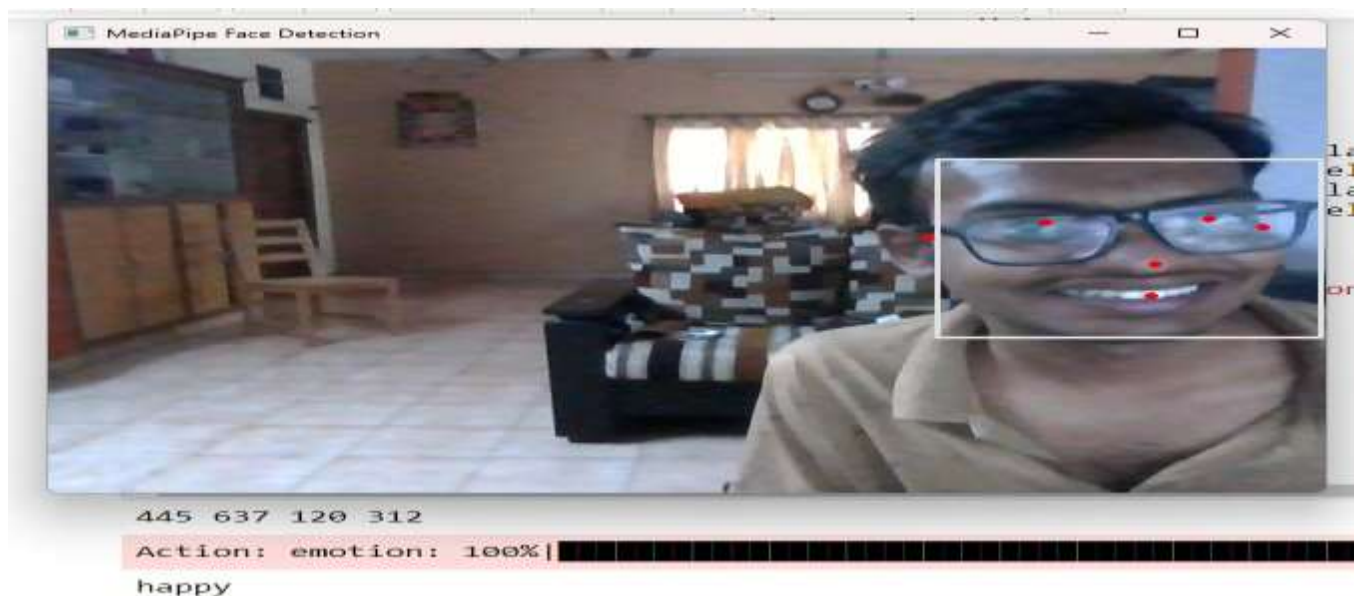


Fig. 13. Execution

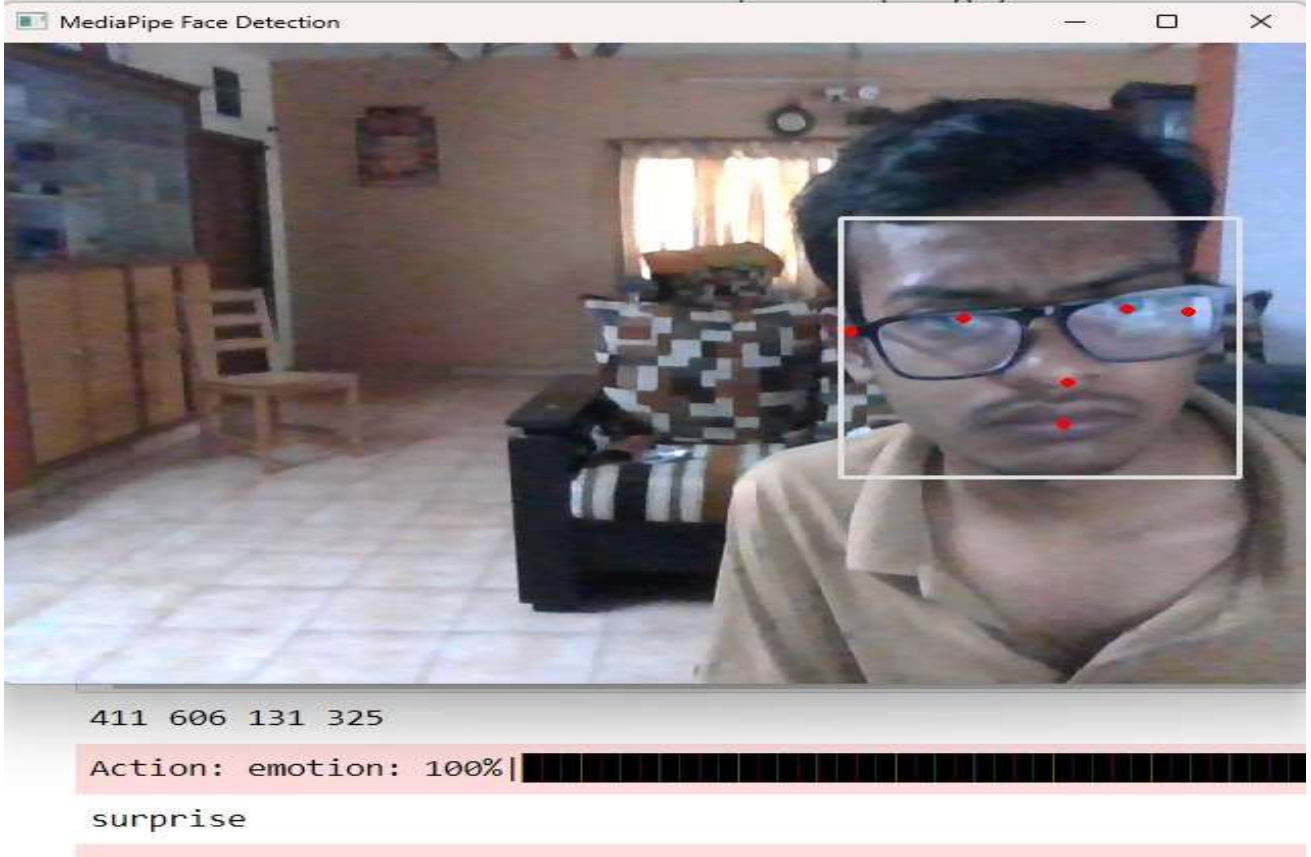


Fig. 14. Execution

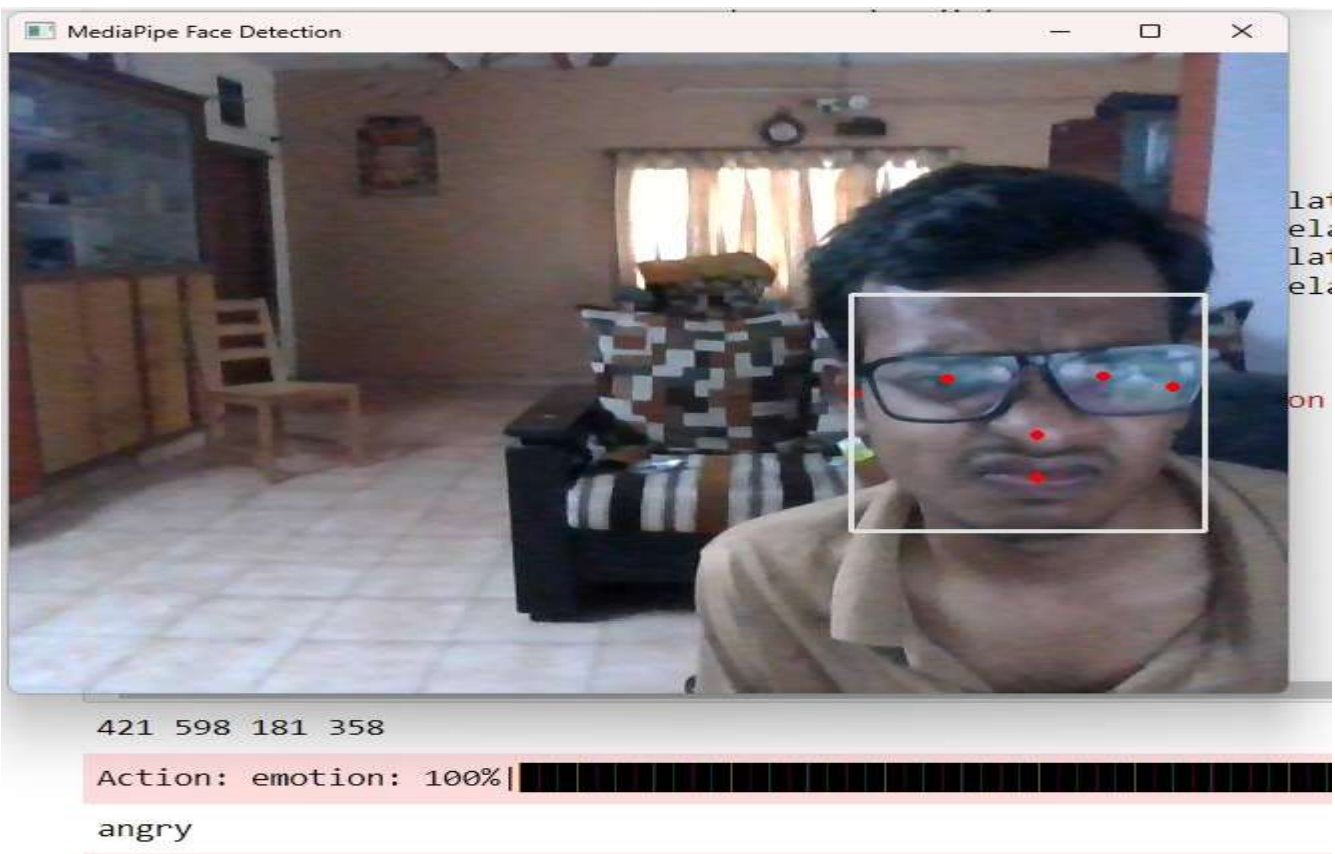


Fig. 15. Execution

## V. TEST CASES

| Test Case ID | Test Case Description             | Test Steps   | Expected Result                                     | Pass/Fail |
|--------------|-----------------------------------|--|---|-----------|
| 1            | Verify Camera Connectivity        | Ensure all cameras are powered on and connected      | All cameras are online and accessible               | Pass      |
| 2            | Test Camera Synchronization       | Simulate an event to trigger camera synchronization  | Cameras synchronize their timestamps                | Pass      |
| 3            | Check real-time Video Streaming   | Access the live video feed from each camera          | All camera feeds are displayed in real-time         | Pass      |
| 4            | Assess latency in stream          | Simulate network congestion or load                  | Measure the latency in video streaming              | Pass      |
| 5            | Test Camera Redundancy            | Disable one of the cameras                           | Verify if the system switches to a redundant camera | Pass      |
| 6            | Evaluate object tracking accuracy | Introduce a moving object within the camera coverage | Verify if the system accurately tracks the object   | Pass      |
| 7            | Wireless connection               | Packets pinging                                      | Uninterrupted data flow                             | Pass      |

## VI. IMPLEMENTATION

In conclusion, the development of a MCN project represents a significant endeavour with vast implications across various domains, from surveillance and security to computer vision and beyond. As we navigate the complexities of this undertaking, several key observations and considerations emerge.

Firstly, the architectural design of a MCN demands meticulous planning, addressing challenges related to synchronization, data fusion, and real-time processing. The deployment of such a network requires careful calibration and maintenance to ensure accurate and reliable performance, minimizing issues related to misalignment or system failures. The integration of computer vision principles, as well as advancements in machine learning and deep learning, plays a pivotal role in extracting meaningful insights from the wealth of visual data captured by multiple cameras.

Techniques such as object detection, tracking, and recognition contribute to the intelligence and efficiency of the system, enhancing its overall functionality. Furthermore, the ethical dimensions surrounding privacy and legal compliance cannot be overstated. Striking a balance between the benefits of surveillance and individual privacy rights is essential, necessitating adherence to regulatory frameworks and the implementation of robust security measures to safeguard sensitive data. While challenges such as cost, scalability, and power consumption present formidable hurdles, ongoing advancements in technology, coupled with a commitment to innovation, offer promising avenues for addressing these limitations.

Potential future developments in the field of MCNs, including:

- 5G Integration: Leveraging 5G technology for high-speed data transmission and low latency.
- Edge Computing: Utilizing edge devices for on-site data processing to reduce network load.
- AI-Driven Insights: Incorporating advanced AI algorithms for real-time decision-making.
- Interdisciplinary Collaborations: Encouraging collaborations between experts from various fields to harness MCNs' full potential.

As we progress, the collaborative efforts of researchers, engineers, and policymakers will likely contribute to refining and expanding the capabilities of MCNs. In essence, a well-executed MCN project has the potential to redefine our approach to monitoring, analyzing, and understanding dynamic environments. The fusion of interdisciplinary knowledge, from computer vision to networking and machine learning, positions such projects at the forefront of technological innovation. As we continue to push the boundaries of what is possible in this field, the impact of MCNs on security, research, and everyday life promises to be transformative, ushering in a new era of visual intelligence and data-driven insights.

#### REFERENCES:

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