



## Some New Results on linear continuous Operators

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### Abstract

In this paper we shall prove If  $E$  and  $F$  are topological vector spaces, then a linear map  $K$  of  $E$  into  $F$  is called compact, if there exist a neighbourhood  $U$  of origin in  $E$ , whose image set  $K(U)$  is relatively compact. Here we find the notion of completely continuous operator to the topological vector space and also the Normed spaces derive a property equivalent to complete continuity.

**Keywords:** Completely continuous, Zero neighbourhood,

### Introduction

A subset  $M$  of a topological space  $R$  is called compact, if every open covering of  $M$  contains a finite sub covering. A subset of a topological space  $R$  is called relatively compact if  $M$  is contained in a compact subset of  $R$ . A subset  $M$  of a topological vector space is called bounded if corresponding to every zero neighbourhood  $U$  there exists a  $\alpha > 0$  such that  $\alpha U \supset M$ .

### Theorem (1.1)

In a Topological Vector space

- Every subset of a bounded set is bounded
- The continuous image of a bounded set is bounded.
- The closed envelope of a bounded set is bounded
- Every compact set  $M$  is bounded.
- The union of finitely many and the intersection of arbitrary number of bounded sets is bounded.
- If  $M, N$  are bounded sets then the sets  $M+N$  and  $\lambda M$   $\lambda \in \mathbb{R}$  are also bounded.

The proofs can be found in Kothe's Topological Vector spaces.

### Theorem(1.2)

If  $E$  and  $F$  are normed linear spaces,  $K$  a linear map of  $E$  into  $F$  and

$$S = \{x \in E : \|x\| < 1\}$$

The closed unit ball of  $E$ , then the following properties are equivalent

( $\alpha$ )  $K$  is completely continuous

( $\beta$ )  $K(S)$  is relatively compact

( $\gamma$ )  $K(S)$  is compact

Here  $K$  is completely continuous iff there exists a neighbourhood  $U$  of origin in  $E$  such that  $K(U)$  is relatively compact.

**Proof**

( $\alpha$ )  $\rightarrow$  ( $\beta$ ): If  $K \in R(E, F)$  and  $\{y_n\}$  a sequence from  $K(S)$ , then there exists  $x_n, n \in N$ , with  $y_n = Kx_n, x_n \in S$ .

Since  $\{x_n\}$  is a bounded sequence, there exists a subsequence  $\{x_{n_k}\}$  such that  $\{x_{n_k}\} = \{Kx_{n_k}\}$  converges to some  $y \in F$ . Then  $K(S)$  is relatively compact.

( $\beta$ )  $\rightarrow$  ( $\alpha$ ): If  $K(S)$  is relatively compact and  $\{x_n \in E : \|x\| = \gamma \neq 0\}$  a bounded sequence in  $E$  then  $\gamma^{-1}x_n \in S$

$K(\gamma^{-1}x_n) \in K(S)$

We can come to the conclusion that there exists a convergent subsequence: therefore  $\{Kx_{n_k}\}$  converges and hence  $K$  is completely continuous.

The equivalence of ( $\beta$ ) and ( $\gamma$ ) are as follows

We now prove the additional proposition. If  $K$  is neighbourhood continuous then  $U=S$  gives the desired results. Conversely, if there exists such a zero neighbourhood in  $E$ , then there exist  $\rho > 0$  with  $\rho S = \{x \in E : \|x\| \leq \rho\}$ . Then also  $(\rho S) \in K(U)$ ; hence

$K(\rho S) = \rho K(S)$  lies in a compact set  $M \cdot \frac{1}{\rho}$ .  $M$  is also compact; as

$K(S) \in \frac{1}{\rho} \cdot M$ ,  $K(S)$  is relatively compact and  $K$  is completely continuous.

In the following we denote by  $R(E, F)$  the set of all compact maps of a topological vector space  $E$  into a topological vector space  $F$ . In case of topological vector spaces, the notion of compact maps is rich in content and more important than the notion of completely continuous maps.

### Theorem (1.3)

- A compact operator is continuous.
- Sum and scalar multiple of compact operators are compact.
- The product of a compact operator with a continuous operator is compact.

In particular,  $R(E)$  is a two sided ideal in the algebra  $L(E)$

**Proof**

(a) If  $K \in R(E, F)$ , then there exists a zero neighbourhoods  $U$  in  $E$ , whose image  $K(U)$  lies in a compact set  $M$  in  $F$ . If  $V$  is an arbitrary zero neighbourhood in  $F$ , then on account of the boundedness of  $M$  there exists  $\alpha > 0$  such that  $M \subset \alpha V$ , therefore  $\frac{1}{\alpha} M \subset V$ . Hence corresponds to zero neighbourhood  $V$  in  $F$ , there exists a zero neighbourhood  $\frac{1}{\alpha} U$  in  $E$  with  $K(\frac{1}{\alpha} U) = \frac{1}{\alpha} K(U) \subset V$ . Therefore,  $K$  is continuous.

(b) If  $K_1, K_2 \in R(E, F)$ , then there exists a zero neighbourhood  $U_1, U_2$  in  $E$  and compact sets  $M_1, M_2$  in  $F$  with  $K_i(U_i) \subset M_i, i=1,2$ . Then the intersection  $U = U_1 \cap U_2$

Is also a zero neighbourhood in  $E$  and it follows that:

$$K_i(U) \subset M_i, i = 1, 2 \quad \mathbf{d}$$

$$\begin{aligned} (K_1 + K_2)U &= \{(K_1 + K_2)x = K_1x + K_2x; x \in U\} \\ &= \{K_1x + K_2y; x, y \in U\} \\ &= K_1(U) + K_2(U) \\ &\subset M_1 + M_2 \end{aligned}$$

But  $M_1 + M_2$  is compact and hence  $K_1 + K_2 \in R(E, F)$ . In a similar fashion we can prove that the  $K \in R(E, F)$  also  $K \in R(E, F), F, \in \emptyset$ .

(c) If  $K \in R(E, F), L \in L(F, G)$ , then there exists a zero neighbourhood  $U$  in  $E$ , whose image  $K(U)$  is contained in a compact set  $M$  in  $F$ . Then also  $L(K(U)) \subset L(M) \subset L(M)$ ,  $L, K$  is Compact.

If  $\alpha \in (E, F), K \in R(F, G)$ , then there exists a zero neighbourhood  $V$  in  $F$ , whose image  $K(V)$  lies in a compact set  $M$  in  $G$ . Since  $L$  is continuous  $L^{-1}(V) = U$  is a zero neighbourhood in  $E$ , therefore  $K(L(U)) \subset K(V) \subset M$ , hence  $KL \in R(E, G)$ .

#### Theorem (1.4)

Every Finite dimensional continuous map  $A \in \Gamma(E, F)$  is compact.

Proof : As  $\dim A(E) < \infty$ , there exists a compact neighbourhood  $V$  of  $0$  in  $A(E)$ ; but the  $V$  is also compact subset of  $F$ . On account of the continuity of  $A$ , the set  $A^{-1}(V) = U$  is a neighbourhood of  $0$  in  $E$  and  $A(U) = AA^{-1}(V) \subseteq V$  i.e  $A(U)$  lies in a compact subset  $V$  of  $F$ , hence  $A \in R(E, F)$ .

In the proof of the continuity of a compact operator we have only used that  $k$  maps a zero neighbourhood into a bounded set.

#### Definition (1.1)

A map  $T \in L(E, F)$  is called bounded, if there exists a neighbourhood of  $0$  in  $E$ , whose image  $T(U)$  is a bounded subset of  $F$ . We wish to denote the set of all bounded operators of  $E$  into  $F$  by  $\zeta(E, F)$ :

$$\Gamma(E, F) \subset R(E, F) \subset \zeta(E, F) \subset L(E, F)$$

From above theorem it follows that a finite dimensional continuous operator is compact, a compact operator is bounded and a bounded operator is continuous.

In contrast a continuous operator need not be bounded. In fact if  $E$  is locally convex but not normable then  $I$  is continuous but not bounded. For if there exists a bounded neighbourhood  $U$  with  $I(U) = U$ ; then by the theorem of Kolmogorov (e.g P f laumann-Unger | 1 |, p.-121 (e) would be normable. Hence in general  $\zeta(E, F)$  is a proper subset of  $L(E, F)$ . In normed linear spaces  $T$  is bounded in the sense of definition iff  $T$  is bounded in the classical in the classical sense, hence in normed linear spaces  $\zeta(E, F) = L(E, F)$ .

#### Theorem (1.5)

- Sums and scalar multiples of bounded operators are bounded
- The product of a bounded operator with a continuous operator is bounded.
- In particular,  $(E)$  is a two sided ideal in the algebra  $L(E)$

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