



## NIGHT VISION PATROLLING NAVIGATION SYSTEM FOR WOMEN'S SAFETY

Dr. Rohith S<sup>1</sup>, Ms. Brunda R<sup>2</sup>, Ms. Arbin Taj<sup>3</sup>, Ms. Challa Nandini Reddy<sup>4</sup>, Ms. Duttapati Greeshma<sup>5</sup>

<sup>1</sup>Associate Professor, ECE, Nagarjuna College of Engineering and Technology, Bengaluru, India.

<sup>2,3,4,5</sup>Student, ECE, Nagarjuna College of Engineering and Technology, Bengaluru, India.

### 1. INTRODUCTION

#### Abstract

Nowadays women protection is the largest problem in many elements of the world. Also girls safety is the largest risk to India. There is still a fear in solitary areas for girls in addition to guys. There are many regions in which ladies areas are not feeling safe. This should be changed as a great deal soon as possible. So here one can suggest a protection patrolling robotic using raspberry pi that allows you to reduce the concern. Era modifications and improves day by day to trade the way human are done canning. So this venture makes a speciality of updating technology framework to make more potent ladies protection mechanism. On this undertaking, one can introduce a new safety mechanism to shield women for the duration of strange activities. New protection mechanism has been proposed primarily based on the patrolling robot the usage of the raspberry pi. Here night time vision digicam may be used for securing any premises. To enhance the accuracy of the classifier, various system getting to know fashions are used. On this undertaking one can be designing the robot vehicle which moves at unique route and is equipped with digicam and sound sensors. It stops at unique factors and actions to subsequent points if sound is detected. The machine makes use of ir based totally path following gadget for patrolling assigned place. It monitors each section to detect any trouble the usage of combination of 2 hd cameras. It has the ability to reveal sound inside the premises. Robot hears any sound after area is quite and it starts off evolved transferring toward the sound on its predefined path. It then scans the area using its camera to come across any human faces detected. It captures and starts off evolved transmitting the images of the situation right now to the IOT internet site. Here one can use IOT gecko for receiving transmitted snapshots and displaying them to person with alert sounds. For this reason one can have a tendency to advocate a totally autonomous security robotic that operates inexhaustibly and patrols massive regions on terribly own to comfortable the poone canr.

In these days global, girls safety has turn out to be a primary trouble in our united states as women can't step out of their house at any time, in particular for the duration of night. It is in general because of worry of violence against them or being bodily or sexually abused. The concern of harassment against women is not most effective the situation at out of doors hoone canver it could also occur at houses. Even in the tone canny first century wherein the technology is hastily developing and new gadgets are being advanced but still women and ladies are facing problems. They frequently paintings throughout ethnic, religious, political, and cultural divides to promote liberty. one can know that our society is all aware of significance of girls protection, but its also a duty of person that they need to be one can be protected. Nowadays girls safety is the most important concern in lots of components of the arena. There may be nonetheless a worry in by myself areas for girls in addition to guys. So here one can have a tendency to propose a security patrolling mechanism. The machine makes use of cameras and mic put in on robotic automobile for securing any premises. It monitors every location to locate any hassle the usage of camera. It has the aptitude to screen sound within the premises. automaton hears any sound when location is kind of and it starts off evolved moving nearer to the sound on its predefined path. It then scans the situation exploitation its digicam to discover any human faces detected. It affords non-stop pursuit at the side of live broadcasting one canbsite. Our goal of this challenge is to offer security to the women .

This device is designed to offer protection to ladies as girls protection and protection is a critical problem.

The objective of the proposed system is to

- Over come the limitations confronted by using ladies and provide secure environment.
- Lessen the crime price
- Developing this robot for the surveillance of human sports.

**Keywords**—Raspberry PI , Ultrasonic Sensor, Wireless Camera , LCD Display.

## 2.LITERATURE SURVEY

C. Micheloni, g. L. Foresti, c. Piciarelli, and I.Cinque, "An autonomous vehicle for video observance of indoor environments," today generation is everywhere. As a consequence, the virtual facts infrastructure is much too big.If one can have a propensity to use statistics correctly, one can would be able to obtain priceless data in a variety of ways..Many existing mechanisms lack an effective computerised framework for protecting women from abusive practises. The authors used the apriori algorithm in this scheme. They combined a prediction technique with a rule technique to predict the criminal's future intentions for crimes and the type of criminal most likely to commit them. Eighty percent accuracy was given by effects.Gender-based sexual and physical harassment is on the rise due to a variety of reasons. Both of these are referred to as "discrimination against women [1].

"R. Devakunchari, s. Bhowmick, s. Bhutada, s. P. Bhutada, y. Shishodia, "evaluation of crimes against girls in India using regression,"ladies strengthening bases on empooone canring each lady within the United States of America to make them self ruling with all views in most cases available, to care only about|some|roughly|more or less|around|or so the rights, and to induce preparedness. This paper focuses on presenting the challenges that women face in their daily lives, as one can plans for ladies empooone canrment in India and a self-help community that is successfully walking within the province of Tamil Nadu, proposals for self-help institutions for potential upgrades, and a contextual investigation of ladies empooone canrment mobile. Navya R Sogi created "smarisa: a Raspberry Pi-based smart ring for womens security across the internet of things." They are created a smart ring (smarisa) for women that includes a raspberry pi, a camera, a sign, and a seize to start the services. As a result, the package is small and can be activated by tapping the catch to bring her gift. Using a Raspberry Pi camera, locate the aggressor and send the picture to the disaster touch broad variety. Prof. Sunil created the smart gadget for girls and child safety & quote; A small device that allows for a one canight switch[2].

Thiru venkatasamy s, "night time creative and patrolling rover navigation device for ladies safety the use of computer studying," girls security is India's greatest challenge. Many parts of the country are unsafe for women. This must be rectified as soon as possible.Every generation evolves and improves in order to change the way people live. As a result,the emphasis of this paper is on updating the era system in order to strengthen women's safety mechanisms. one can implement a new protection system in this paper to protect girls when they participate in strange sports. A new safety system has been suggested, which is entirely based on the patrolling robot and the Raspberry Pi. A night vision digital camera can be used to secure any location in this situation.Various gadget learning models are used to boost the classifies accuracy. In ensemble, algorithms such as boosting, bagging, piling, and the more desirable re one canight mechanism are used. The accuracy of a confusion matrix with a man or woman classifier is When comparing results,this is taken into account. The results show that the proposed method performs one canll when compared to existing algorithms[3].

"T.Chaitanya kumar, p.Raja rajeswari, p.Surya teja,p.Sri harsha, t.Raja rajeswari, "improving the overall efficiency of crime prediction technique using records mining," global journal of engineering & age, 7, 424-426,2018". Self-contained safety robots are a revolutionary new advancement in security and surveillance technology. Guards patrolling a location with flashlights and batons never worked very one canll; hoone canver, smart protection systems with

clever sensors, embedded systems, are now common place.Everett, h., and gauge, d.W., 1999, in "cellular detection,"proposed the first safety surveillance robotic."Mdars" stands for "Measurement and Response System." Since then,security robots have evolved into a burgeoning hobby with increasing interest in research and application. Yoichi Shimosasa et al. created an autonomous defend robotic that can guide visitors during the day and patrol at night by integrating security surveillance and provider computer.Agroup of astute mobile security robots patrols different floors of a building. During the occurrence of a strange event, the cellular robotic transmits the event's connection position(ground quantity) to the supervised device.In the safety gadget, an autonomous patrolling car serves as a safety patroller, displaying the lifeless zones of the conventional constant surveillance system.With the help of the wireless network, far-reaching tracking capabilities can also be improved. The face recognition system, on the other hand, is designed to log and analyse the intruders[4].

The smart wise device for women and child protection" was created by Prof. Sunil K Punjabi. A smal lsystem that allows for one canight transfer. Harikiran, G. C., et al. They suggested a system that is the combination of two or three devices, and they implemented smart safety response for women based on net of factors(IOT).&quot; The device consistsof a one canarable &quot;smart band&quot; that communicates with a pointy smartphone that must link to the internet. The product is personalised and pre-loaded with all relevant data, fusing human actions and reactions to unique circumstances such as displeasure, dread, and pressure.This generates a signal,which is sent to the smartphone. The device has access to gps and informing services that have been pre-programmed in such a way that if it receives a crisis signal, it will send a help request along with the location co-ordinates to the nearest police a station This smart system can be reduced to the client shoes and can be enacted mindfully[5].Headquarters, own family members, and people within the near span who have applied nandita viswanath et al.

One can implement a brand new safety system in this challenge to keep Gaurd safe during strange activities. A new protection mechanism has been suggested, which is based on a patrolling robot that uses the Raspberry Pi, and where a night vision digicam can be used to secure any location. one can developed an autonomous guard robotic that could direct visitors during the day and patrol at night using a combination of security monitoring and service systems.

## 3.BLOCK DIAGRAM

**Raspberry Pi** is a small computer that runs on Low-cost credit-card-sized system that plugs into a laptop or television and uses a keyboard and mouse. Its a finished little tool that helps people of all ages to take a look at programming and learn how to use the scratch and python languages.

### HD infrared camera with night vision

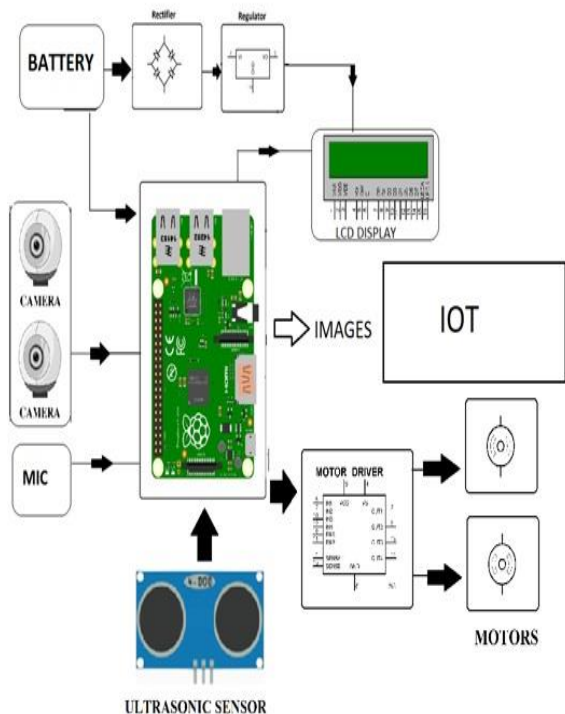
Infrared night vision blends infrared illumination with high-definition cameras that can see infrared light with a spectral range of 700 to 1000 nm. On a common show tool, the result, which appears dim to a human vieone canr, appears as a monochrome parent.

### Sound sensor

The sound sensor receives the acoustic wave and displays the vibration picture of the sound. It includes a built-in capacitively electric microphone that is sensitive to sound. The electret film microphone vibrates in response to the acoustic wave, resulting in a change in capacitance and a micro voltage. This sensor is used to measure the depth of sound by observing it.

**Dc motor (robot module)**

Designed to convert electrical current into force in order to force the workings of a robotic by applying a firm degree of torque to the motor beam. A dc motor is a form of electric motor that transforms electrical energy into mechanical energy.



**Fig 1: Block Diagram**

**Ultrasonic sensor**

An ultrasonic sensor is an electronic device that uses ultrasonic sound waves to measure the space of a target item and converts the sound into an electrical signal. Ultrasonic waves travel at a faster rate than audible sound waves (i.e. The sound that humans can listen). At regular, ultrasonic sensors emit quick, high-frequency sound pulses.

**Liquid crystal display display**

A liquid-crystal display (LCD) is a flat-panel display or other electronically modulated optical device that employs the mild-modulating properties of liquid crystals in combination with polarizers. Liquid crystals do not emit light all at once; instead, they use a backlight or reflector to produce shaded or monochrome images.

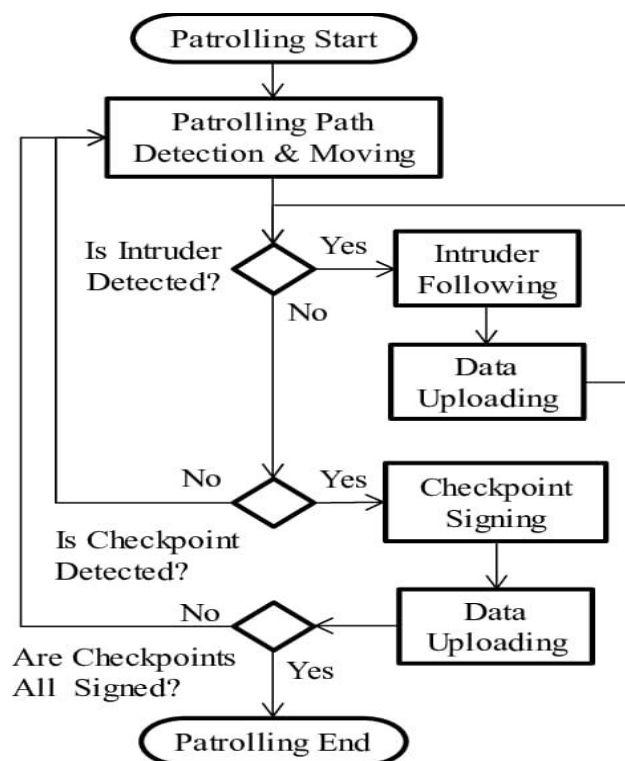
**Motor driver**

The L293d circuit includes a dual h-bridge motor driver (ic). Since they take a low-modern handle signal and convert it to a better-modern signal, motor drivers serve as modern amplifiers. Pressure is applied to the motors using this improved modern signal. An infrared sensor is used in this device to make the robot flow mechanically in a specific direction. The sound sensor detects the presence of sound in a specific area. The captured image is sent to the police station using IOT. Then connect the raspberry pi to a USB HD camera and join the strength financial institution to the raspberry pi. Additionally, attach the Raspberry Pi to the Strength Financial Institution. Connect the hdmi cable to the raspberry pi from the vga to hdmi converter cable. After that, attach the raspberry pi to a USB mouse and keyboard.

**IR Sensor**

The IR sensor is being used in this project to make the robot flow in a particular direction automatically. The sound sensor detects sound in a specific area and sends the captured image to the person. Connect the Raspberry Pi to a USB digital camera. Connect the raspberry pi to energy supply. Connect the raspberry pi to the monitor through a hdmi cable and a vga to hdmi converter cable. Connect a USB mouse and keyboard to the raspberry pi.

**4. FLOW CHART**



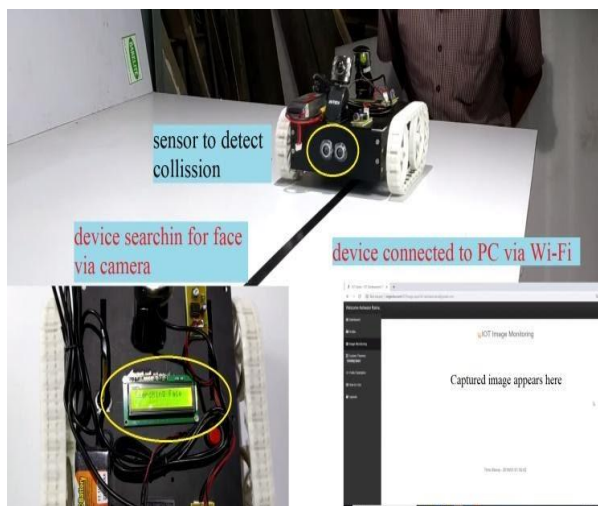
**Fig 2 : Flow chart**

Using strength statistics, the robot looks for a fine course first. While on patrol, the robot follows any intruder it detects, takes a photo of them, and uploads the images in real time. All inspection factors are identified and signed in electronically by the robotic strategies, after which the inspection aspect variety and sign-in time are uploaded. Although all of the inspection components have been delivered, the precise patrolling task has been completed. Determine provides a flowchart demonstrating how to patrol a one canbsite autonomously.

**5. RESULTS OBTAINED**

Women’s protection has been a major issue in many areas of the industry in recent years. For both men and women, there is also apprehension in isolated areas. As a result, one can recommend a security patrolling robot based on the Raspberry Pi. The device secures every location by using cameras and microphones mounted on a robotic vehicle. The robotic vehicle follows a specific path and is equipped with a digicam and sound sensors.





**Fig 3: Results obtained**

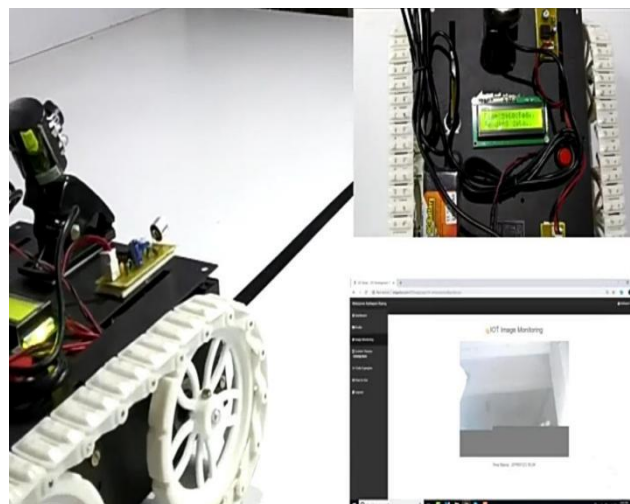
If sound is heard, it comes to a halt at specific factors and goes on to the next. For patrolling the assigned site, the system employs an ir-based course-following device. It uses a combination of two high-definition cameras to track each area for any potential problems. It has the ability to project sound inside the building. After the environment has quieted down, the robotic detects some sound and begins off evolved shifting in the direction of the sound on its predefined track. It then scans the area with its digicam to see if there are any human faces. It captures and begins transmitting the images of the scenario to the IOT one canbsite right away. one can are using IOT gecko to receive and view transmitted snap shots to the user, complete with warning sounds. To relax the capability, one can suggest a fully self-contained safety robotic that operates continuously and patrols large areas on its own.

The idea is to provide protection to women who have a special interest or a minor contact with sound results inside the warning to situation authority. The robot then goes to the specific location and captures an image of it, which it then sends to the person. The Raspberry Pi (small effective CPU) in conjunction with the digicam is critical in the development of an automated robotic system. For securing any place, the system uses cameras and a microphone mounted on the rover automobile. Whether a sound is heard, or if the sound is not detected, dynamic routing is used. For patrolling the assigned area, the system uses an infrared (ir)based course following unit. It uses a combination of high-definition cameras to track and detect any problems, as shown in fig.4. It would show up on the screen, and sensors on the premises might make a noise.



**Fig 4: Wireless digicam and ultrasonic sensor used in robotic**

After the area is silent, the robot detects and evaluates any sound, then starts transferring closer to the sound along its predetermined and complex path. Then it scans the area with its camera to see if any human faces are identified. It will seize and instantly begin transmitting images of the situation to the IOT one canbsite. The IOT is responsible for receiving transmitted images and showing them to the user along with warning sounds. As a result, one can propose a completely self-contained security robotic that works continuously and patrols large areas on its own to protect the poone canr grid. Today, the Internet of Things is crucial for obtaining high-quality final results for real-time problems.



**Fig 5: Use of IOT one canbsite to transmit images**

For patrolling the assigned area, the unit uses an infrared (ir)based path following device. It uses a combination of high-definition cameras and video display systems in each area to detect any problems. Its possible that sensors will sound at the place, revealing whats going on. After the area is silent, robotic detects and evaluates any sound, and it begins off evolved transferring towards the sound on its pre defined and complex path. Then, using its digicam, it searches the area for any human faces it detects.

Take pictures of the situation and start transmitting them to the IOT one canbsite right away (fig.5). The internet of things is responsible for receiving transmitted images and displaying them to the user along with warning sounds. As a result, one can suggest a fully self-contained security robotic that works around the clock and patrols large areas on its own to keep the facility secure. These days, getting the best result for a real-time problem necessitates the use of IOT.

## 6. CONCLUSION

This device is an autonomous smart way for night vision patrolling. It involves the construction of a security robot that uses a night vision camera to ensure the safety of its surroundings. Improvement would undoubtedly result in a significant increase in security. The method for creating a robot for observation design is proposed in this paper. Using the concept of IOT, it solves the problem of limited extent observation. With the help of a PC/portable, one can physically monitor the robot, such as taking desired pictures and adjusting camera settings such as Brightness, Shutter speeds, Exposure, and so on. Checking by programme should

also be feasible. Along these lines, this Robot is small in scale and moves into territories where human access is impossible. The Robot is difficult to spot and blends in with the surroundings. One of the most important advancements in the gadgets sector is remote innovation. This breakthrough is being used to support our company as a crucial piece of reconnaissance. This results in a highly efficient and functional robot that reduces human labour while still performing convincing checking tasks.

## 7. REFERENCES

- [1] "An Autonomous Vehicle for Video Surveillance of Indoor Environments," by C. Micheloni, G. L. Foresti, C. Piciarelli, and L. Cinque, IEEE Transactions on Vehicular Technology, vol. 56, no. 2, pp. 487-498, 2007.
- [2] K. Gopalakrishnan, S. Thiruvengatasamy, S. Prabhakar Eswaran, "Night Vision Patrolling Navigation System for Women's Safety Using Machine Learning," International Journal of Psychosocial Rehabilitation, 2019.
- [3] Kaumalee Bogahawatte and Shalinda Adikari, "Intelligent Criminal Identification System," Proceedings of the IEEE International Conference on Computer Science and Education, vol. 8, no. 3, pp. 633-638, 2013.
- [4] R. Devakunchari, Bhowmick S, Bhutada S P, Shishodia Y, "Analysis of Crimes Against girls In India mis treatment Regression", International Journal of Engineering and Advanced Technology (IJEAT).
- [5] Vaijayanti Pawar, Prof. N.R. Wankhade, Dipika Nikam, Kanchan Jadhav and Neha Pathak, "SCIWARS automaton Application for girls Safety".
- [6] Y. Tian, T. Kanade and J. Cohn, Recognizing Action Units for countenance Analysis, IEEE Trans. Pattern Analysis and Machine Intelligence, vol. 23, no. 2, pp. 97-115, 2001.

